

# GNSS/GALILEO Technology Helpful for Precision Farming

(i.e. GNSS as an Earth's Remote Sensing Tool)

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# Content

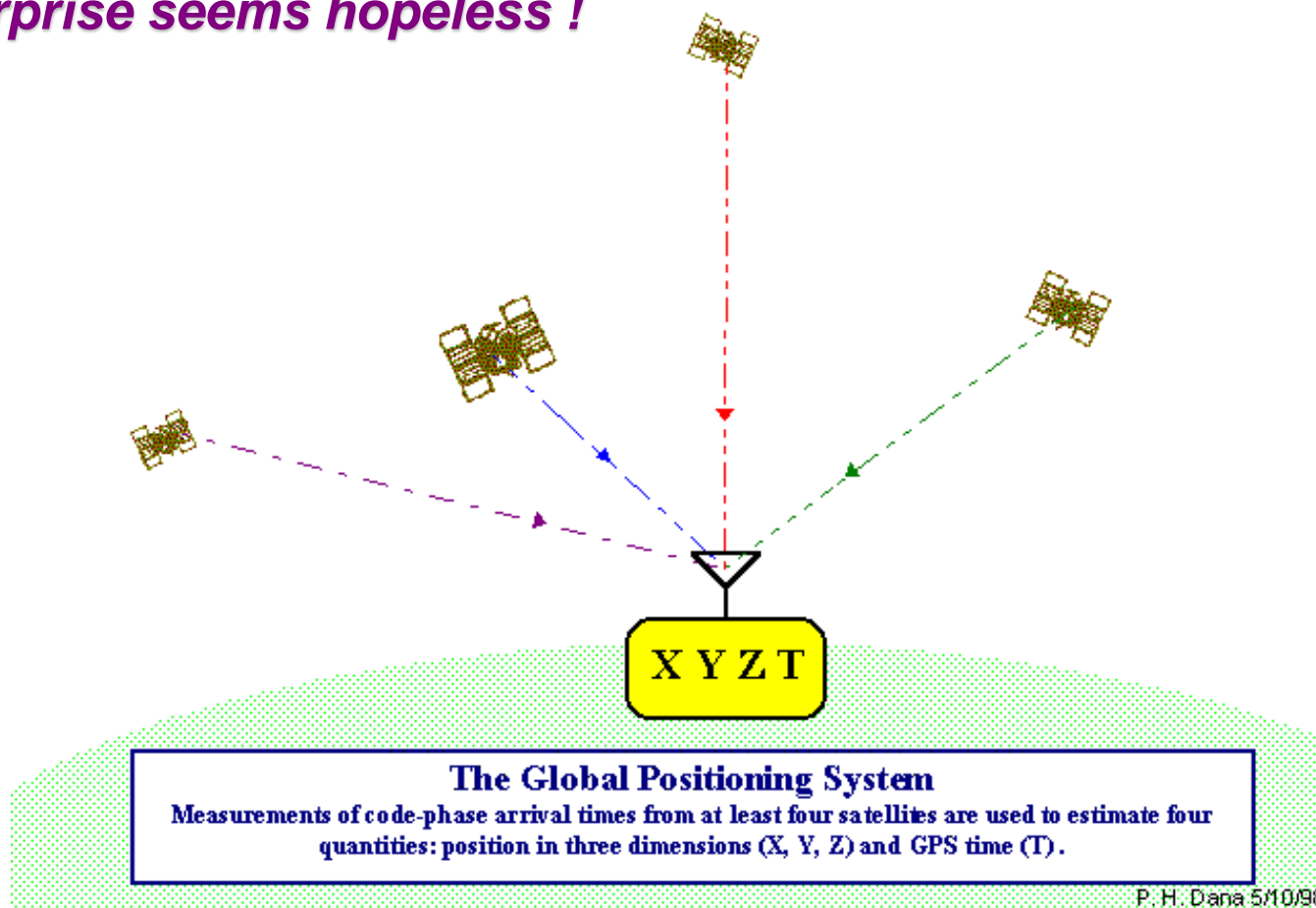
- Brief Description of GNSS Systems
- Potentials App. of GNSS with Zenith Pointing Antennas (Ground and Spaceborne)
- .....with Limb Pointing Antennas (GNSS -RO)
- .....with Nadir Pointing Antennas (GNSS-R)
- Focus on Precision Farming applications
- Conclusions

# Potentials App. of GNSS with Zenith Pointing Antennas (Ground and Spaceborne)

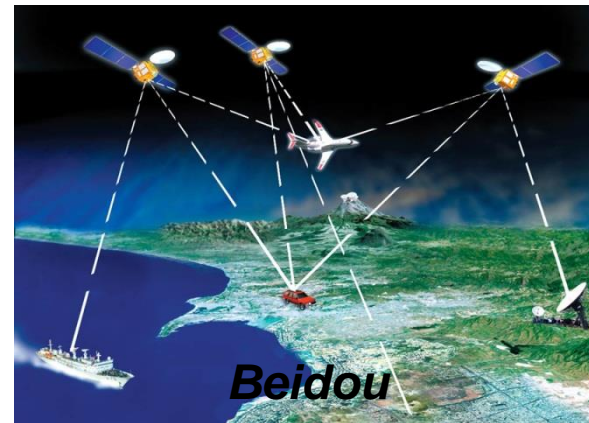
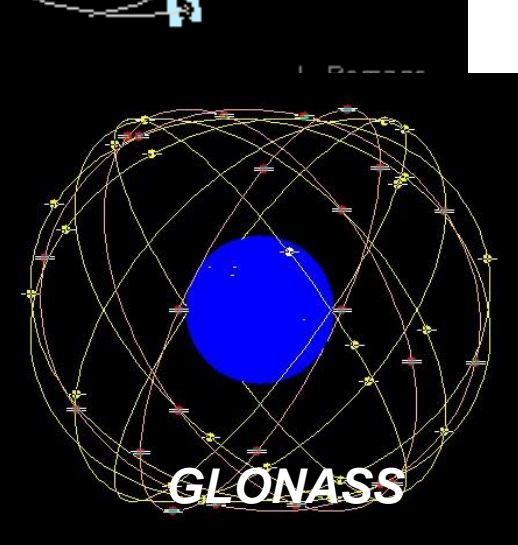
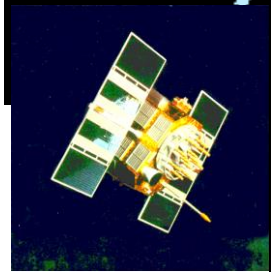
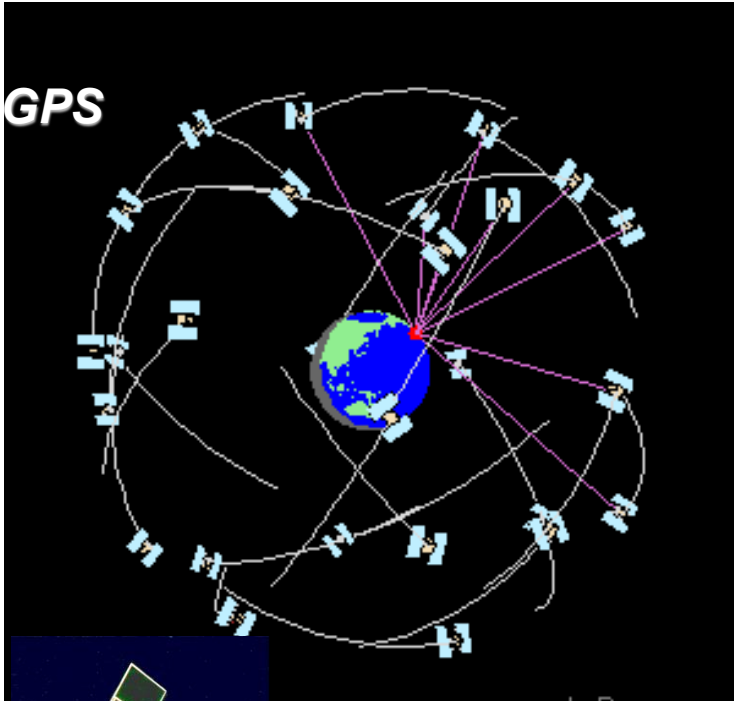


# The Global Navigation Satellite Systems: The Principles

**Accuracy "few meters**  
**The enterprise seems hopeless !**  
**But.....**



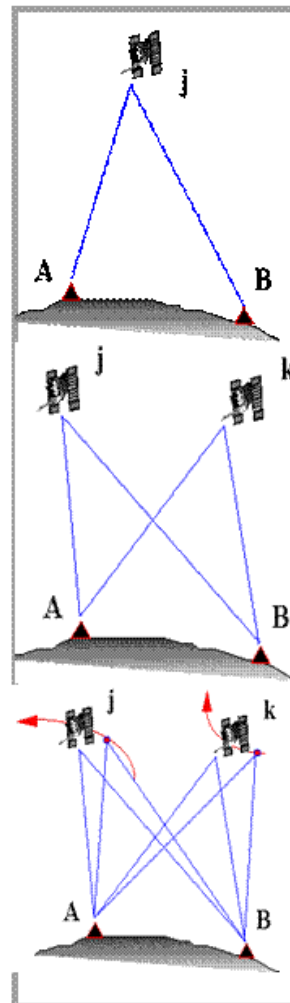
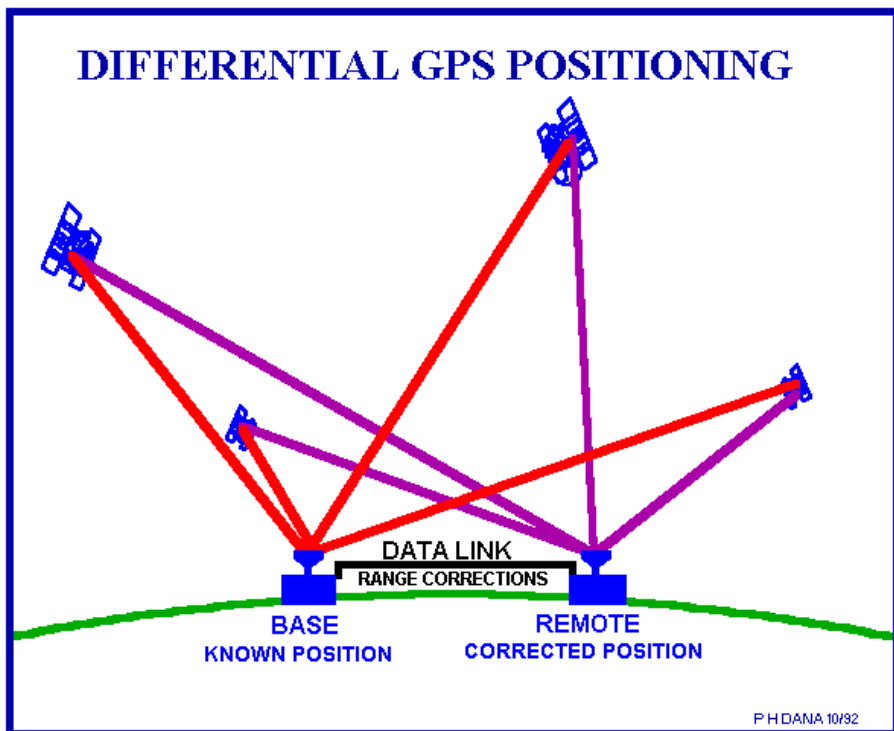
# Space Missions:



18/11/201

Space Technologies meet  
Agriculture

# The Differential Approach



**Single Differences**  
 These are used to reduce satellite clock and orbit errors, and localised atmospheric errors.  
 This is the technique used by DGPS.

**Double Differences**  
 These are used to reduce satellite clock and orbit errors, localised atmospheric errors, and receiver clock errors.  
 This is usually the technique adopted by the final carrier phase GPS solution. Relative GPS also uses this approach.

**Triple Differences**  
 This is the difference between two double differences from measurements recorded at subsequent epochs.  
 Assuming no cycle slips, or loss of lock has occurred, this eliminates the integer ambiguity. It is therefore used to detect for cycle slips and loss of lock.

*The uncertainties are reduced at few mm level !!*

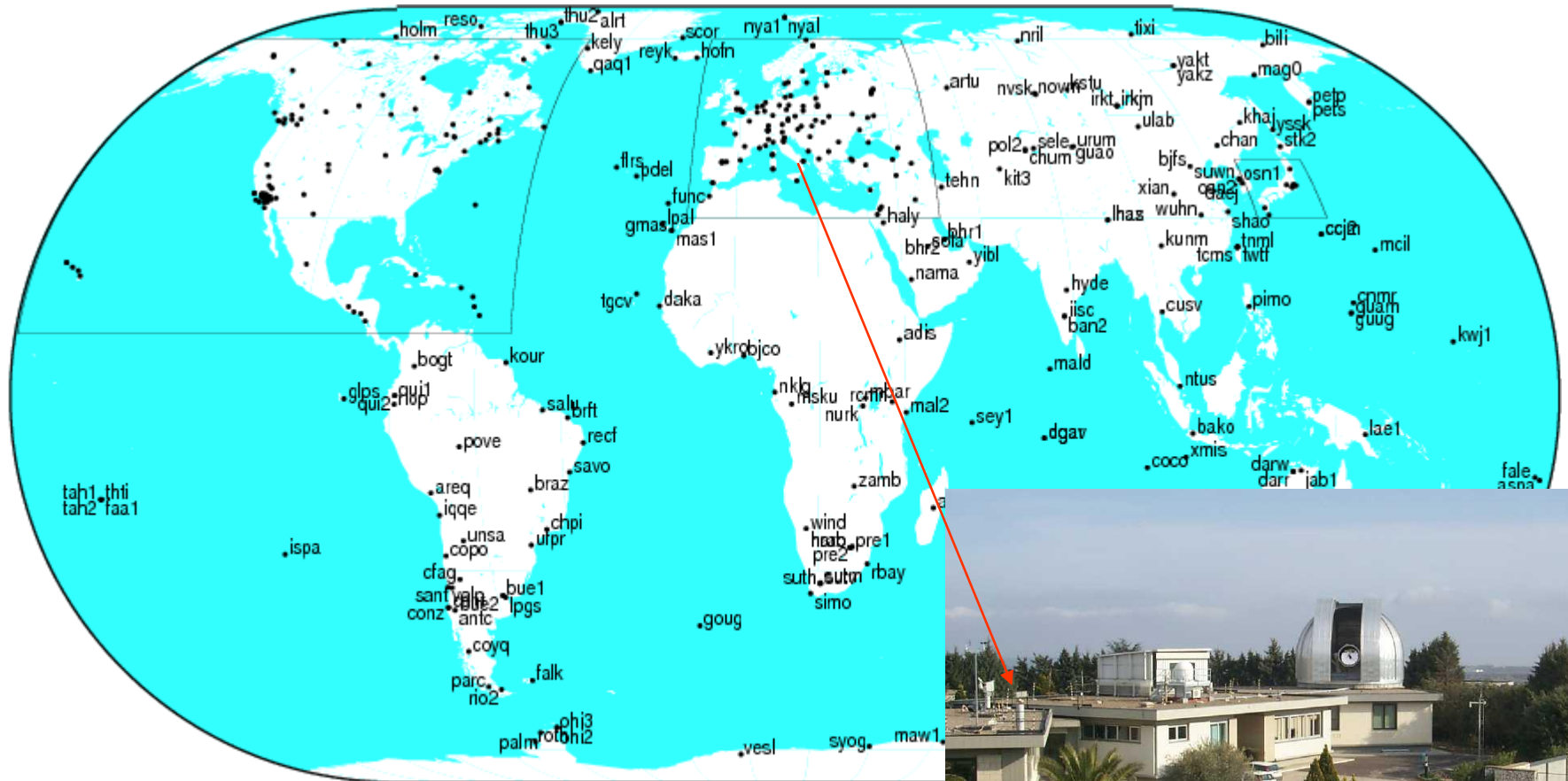
# Survey modes

## Performances of GPS Survey

- 2-3 mm horizontal in PP
- 4-7 mm height in PP
- 1 cm < 30' of data
- 5 cm in RTK
- Continuous acquisition 24/24 365/yr
- Very long baselines > 1000 Km

	<p><b>Continuous Kinematic</b></p> <p>After initialisation, or resolution of the ambiguities, one receiver is allowed to roam. You must however keep track of the satellites so that lock is not lost, and only few cycle slips occur.</p>
	<p><b>Pseudo Kinematic</b></p> <p>This allows you to compute the coordinates of a large number of points without observing a static network. You set up for approximately one minute twice on each of the points you wish to be coordinated. The two occupations of a point must be separated by at least one hour in time.</p>
	<p><b>Semi Kinematic/Stop and Go</b></p> <p>Here you spend a few minutes on each point. When moving between points you must still keep lock on the satellites, although positions are not computed.</p>

# 1991 Matera GPS Station became part of IGS network



GMT 2011 Mar 13 16:45:38

18/11/2016

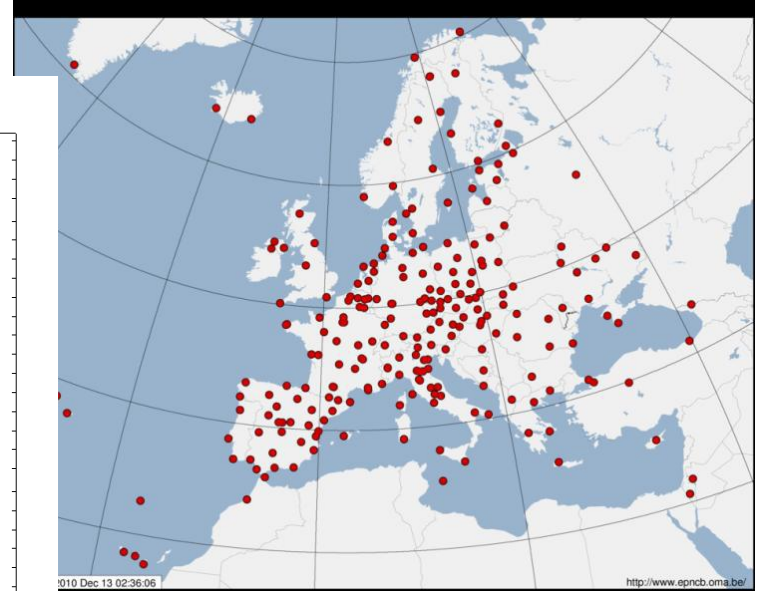
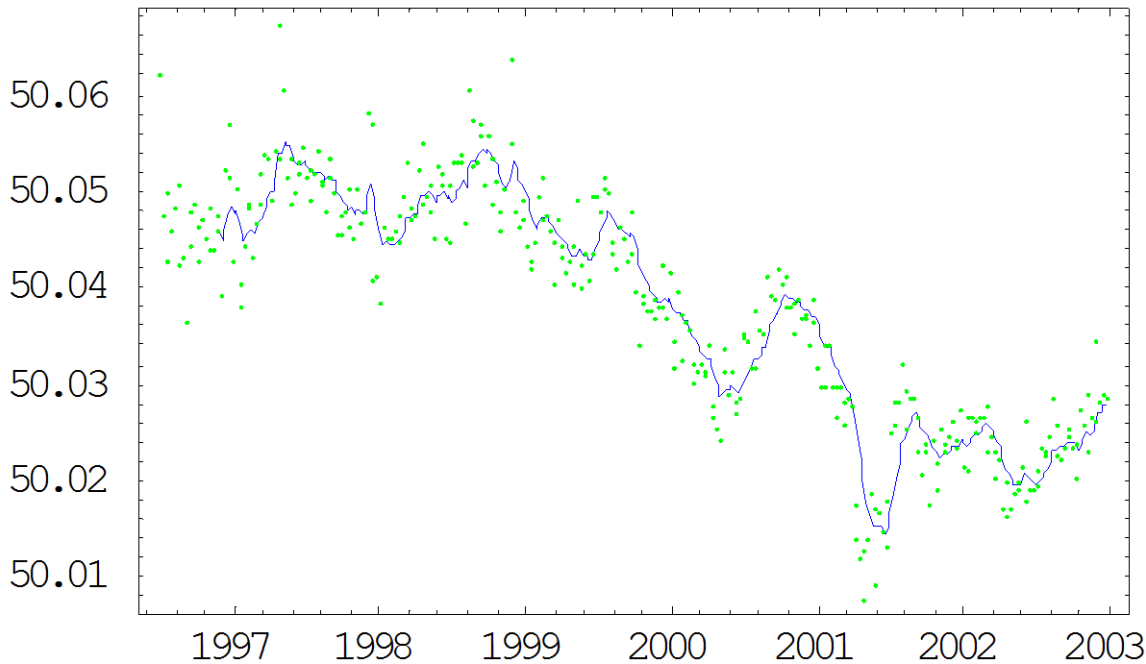
When Space Technologies meet Agriculture



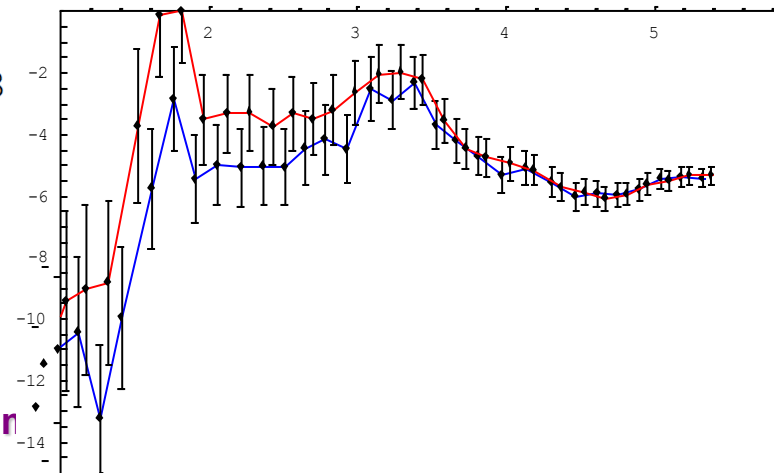


# 1996 ASI joined EUREF service as Local Analysis Center

Medi

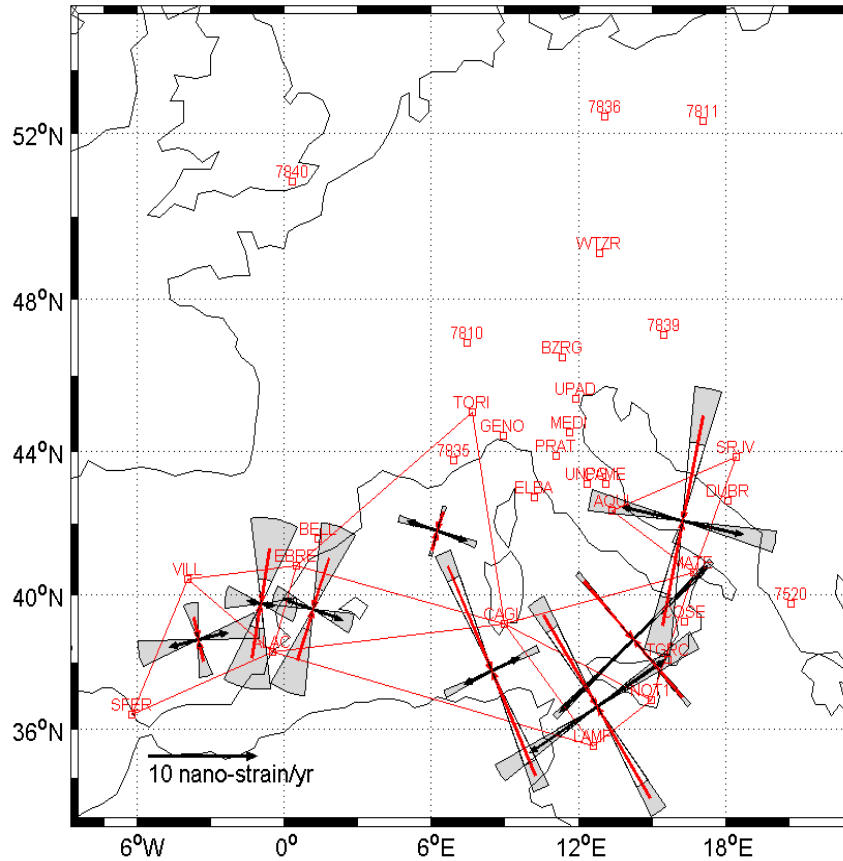


$$V_{tot} = V_{tect} + V_{sl} + V_{sc} + V_{pgr} + V_{wl} + V_{antr.}$$



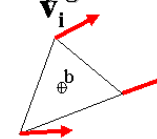
# Seismicity

## Strain rate in the Western Mediterranean Area



## Strain Rate Computation

- 1 The planar (x,y) velocities in the vertices of each selected triangle are expanded at the first order by means of the velocity gradient tensor  $L$



$$\mathbf{v}_i = \mathbf{L} \Delta \mathbf{x}_i + \mathbf{v}_b$$

$$L = \begin{bmatrix} \frac{\partial V_x}{\partial x} & \frac{\partial V_x}{\partial y} \\ \frac{\partial V_y}{\partial x} & \frac{\partial V_y}{\partial y} \end{bmatrix}$$

- 2 Estimation of the tensor  $L$  in a least squares sense

- 3 Strain rate ( $E$ ) computation

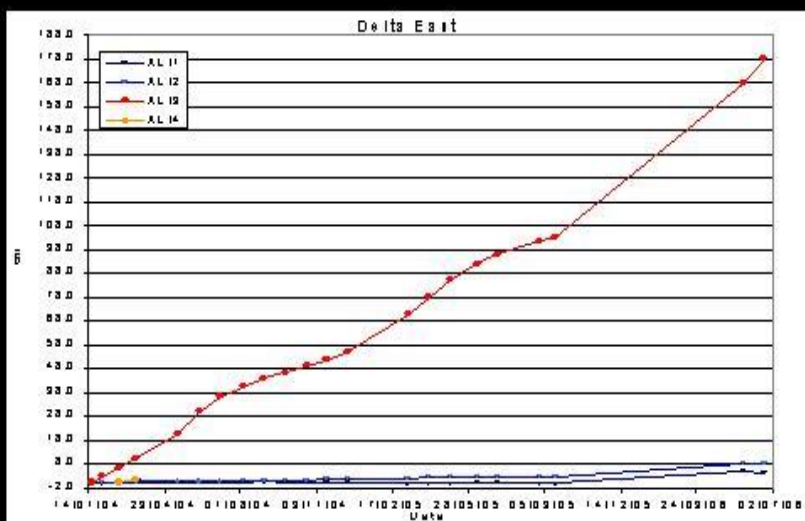
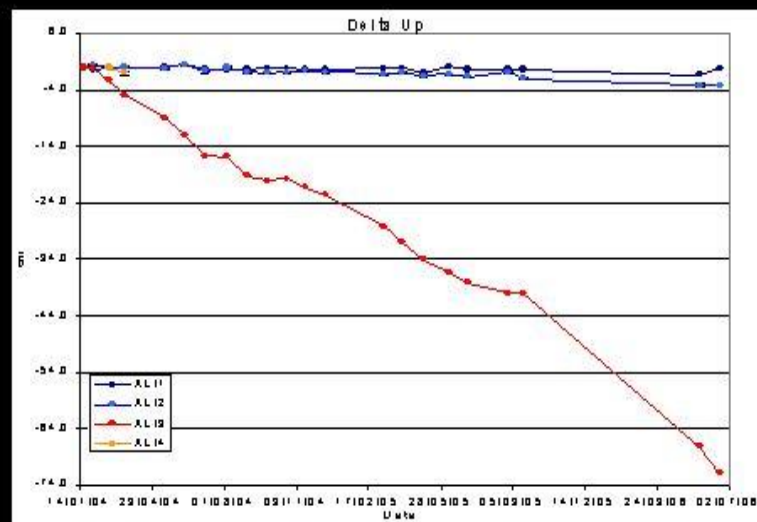
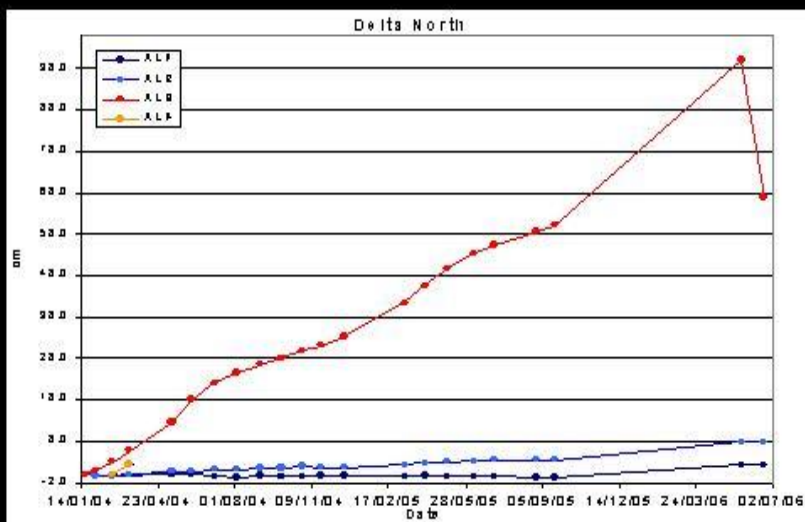


$$E = \frac{1}{2}(\mathbf{L} + \mathbf{L}^T)$$

- 4 Measurement unit of strain rate: 1 nano-strain/yr is equal to a deformation of 1mm/yr per 1000 Km

# Landslides

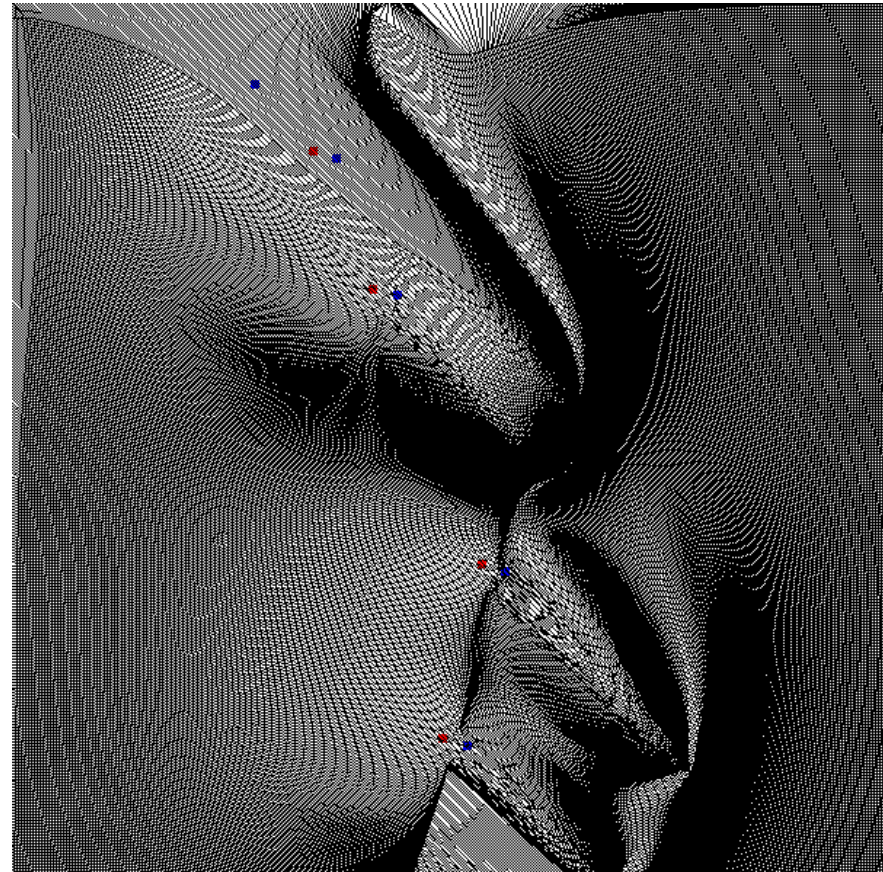
## Aliano



# Extension of the experiment to Craco (Mt)



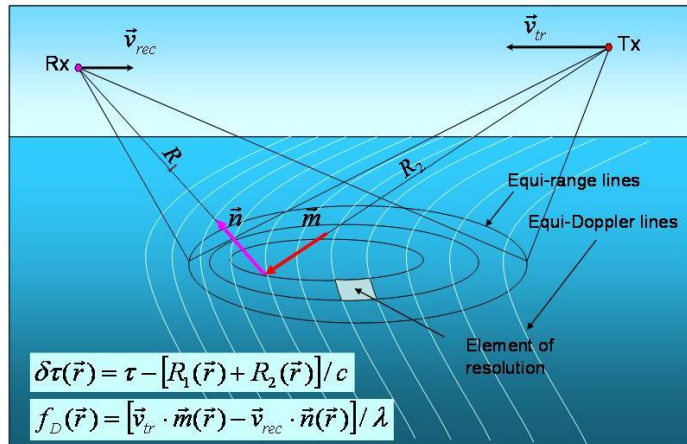
*A site Included in  
WMF list*



# Livello del Mare/Erosione delle Coste

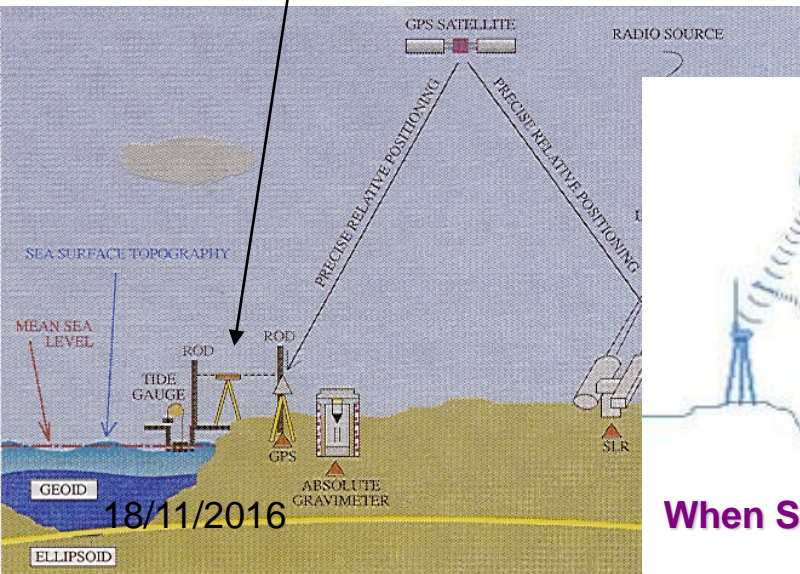
## Uso modalità Bi-statica

## Linee di costa

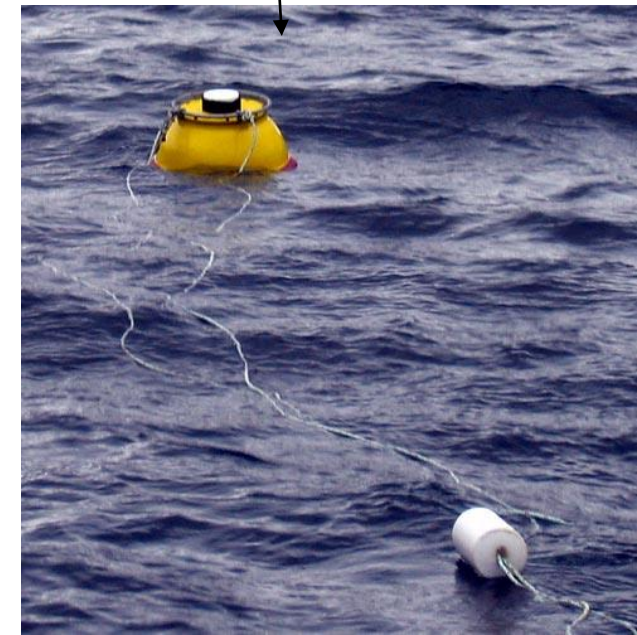
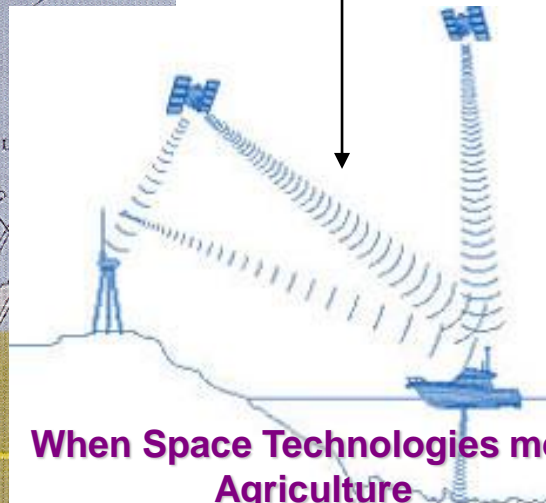


Boe Marine GPS  
Moto Ondoso, Maree,  
Allarme Tsunami, ecc.

## Co-localizzazione con Mareografi



## Batimetria



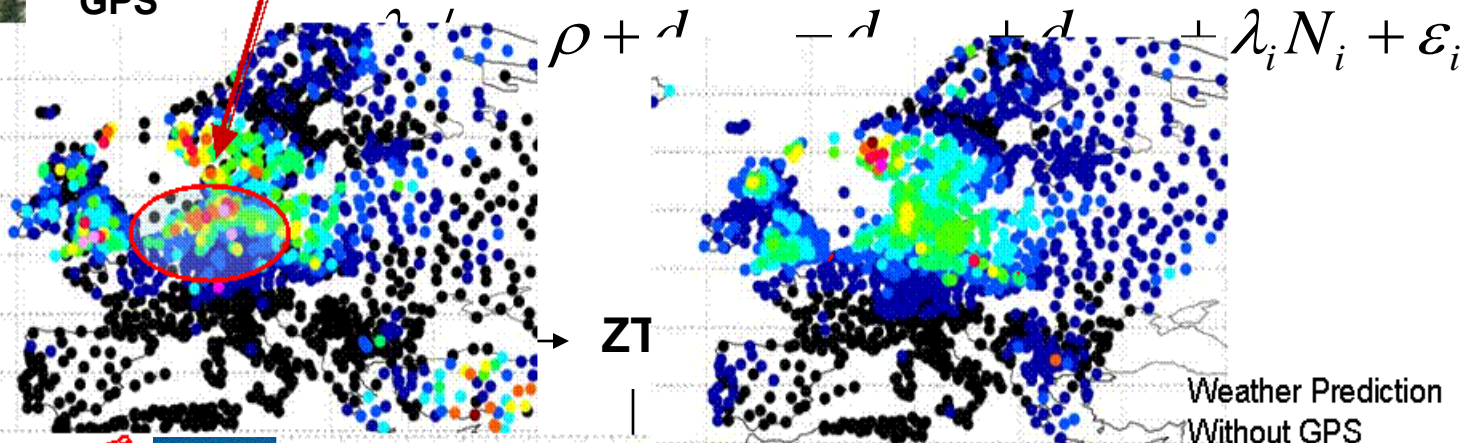
# Meteorology

## From GPS observable to NWP assimilation



GPS

Severe Precipitations



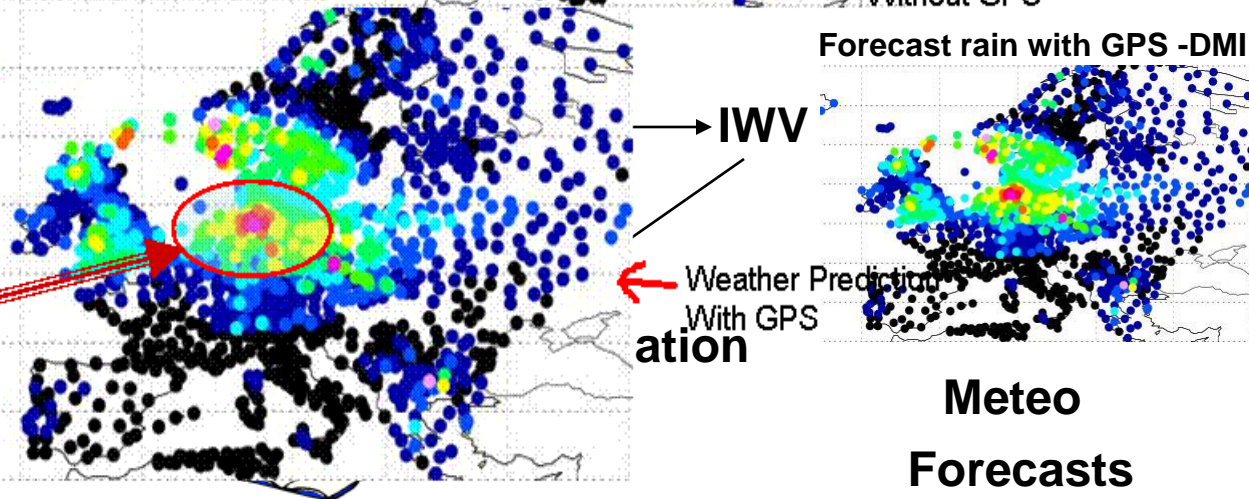
Weather Prediction Without GPS



Observed Precipitation



Severe Precipitations



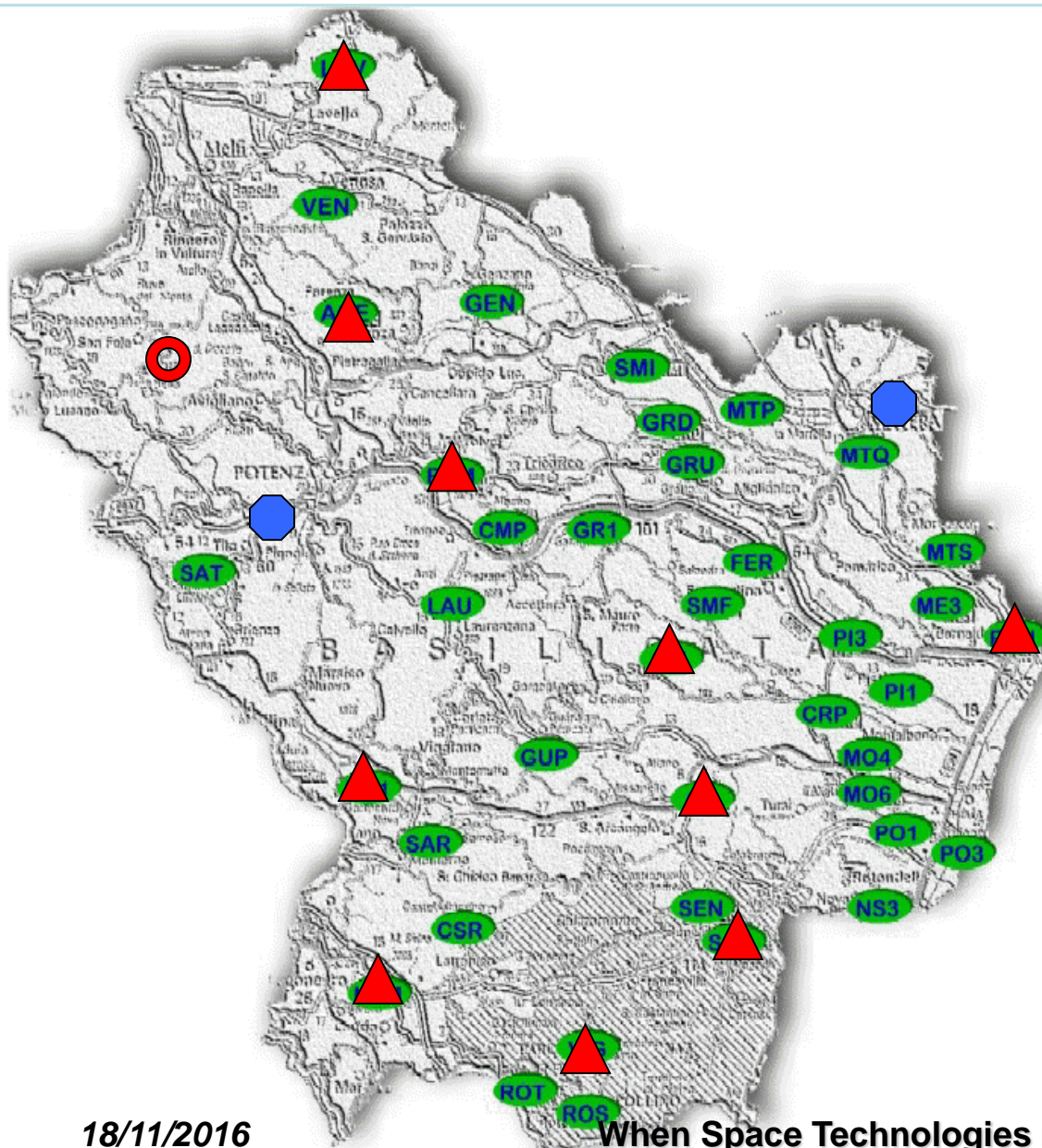
Forecast rain with GPS -DMI

IWV

Weather Prediction With GPS

Meteo Forecasts

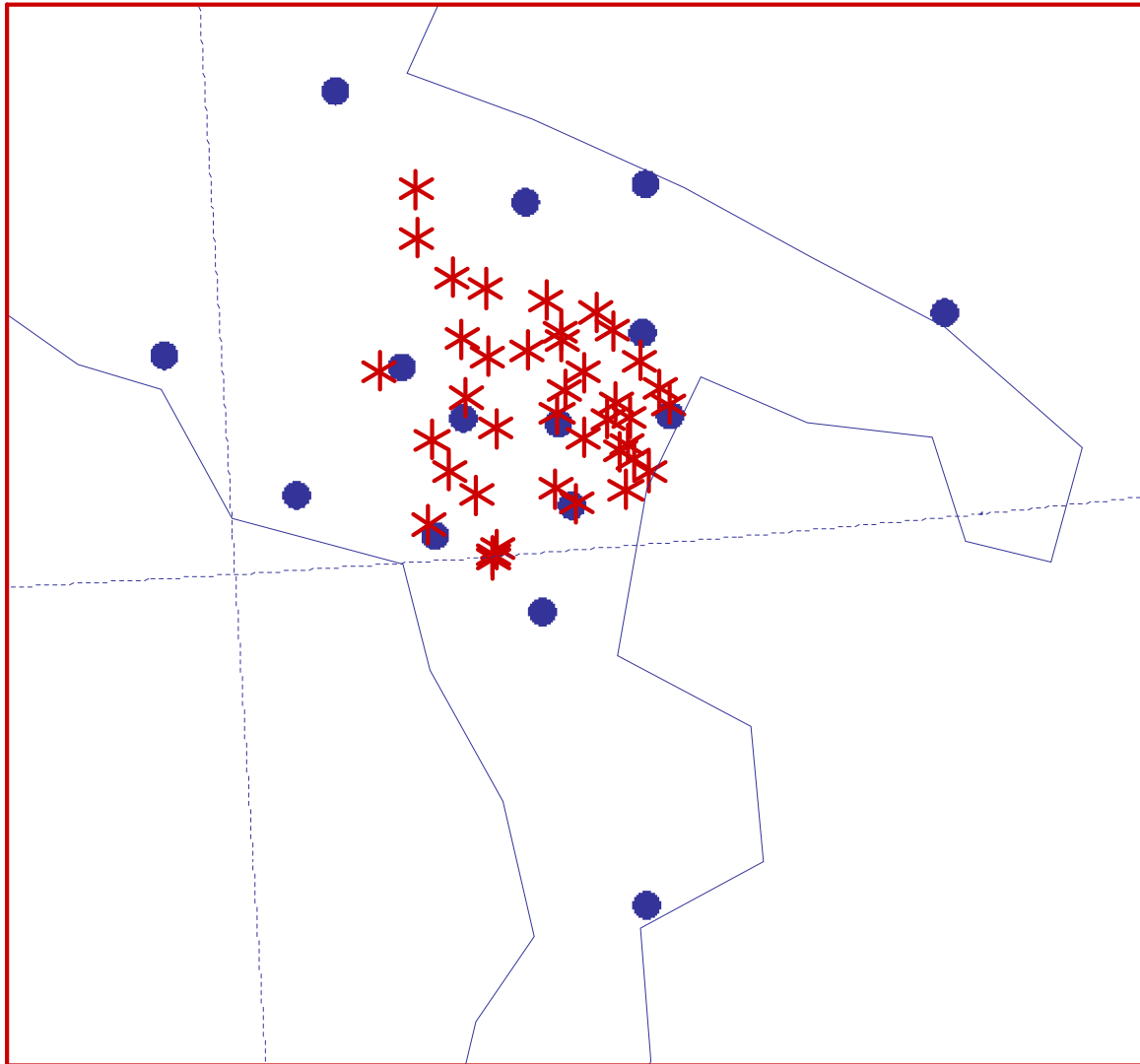
# Il Progetto MAGIC II



<b>Siti ALSIA selezionati ▲</b>		
Lavello	(LAV) q.s.m.	300 m
Brindisi di Montagna	(BRM) q.s.m.	900 m
Marsico Vetere	(BG1) q.s.m.	1000 m
Aliano	(ALI) q.s.m.	600 m
Nemoli	(NEM) q.s.m.	700 m
Viggianello	(VIG) q.s.m.	550 m
S. Giorgio Lucano	(SGL) q.s.m.	400 m
Metaponto	(PAN) q.s.m.	30 m
Stigliano	(STI) q.s.m.	1000 m
Acerenza	(ACE) q.s.m.	300 m
<b>Ulteriori siti disponibili ●</b>		
Matera	(CGS) q.s.m.	500 m
Tito	(TIT) q.s.m.	600 m
<b>Siti completamente da installare ○</b>		
Toppo di Castelgrande		

# Rete di stazioni GPS e Pluviometri

15 E

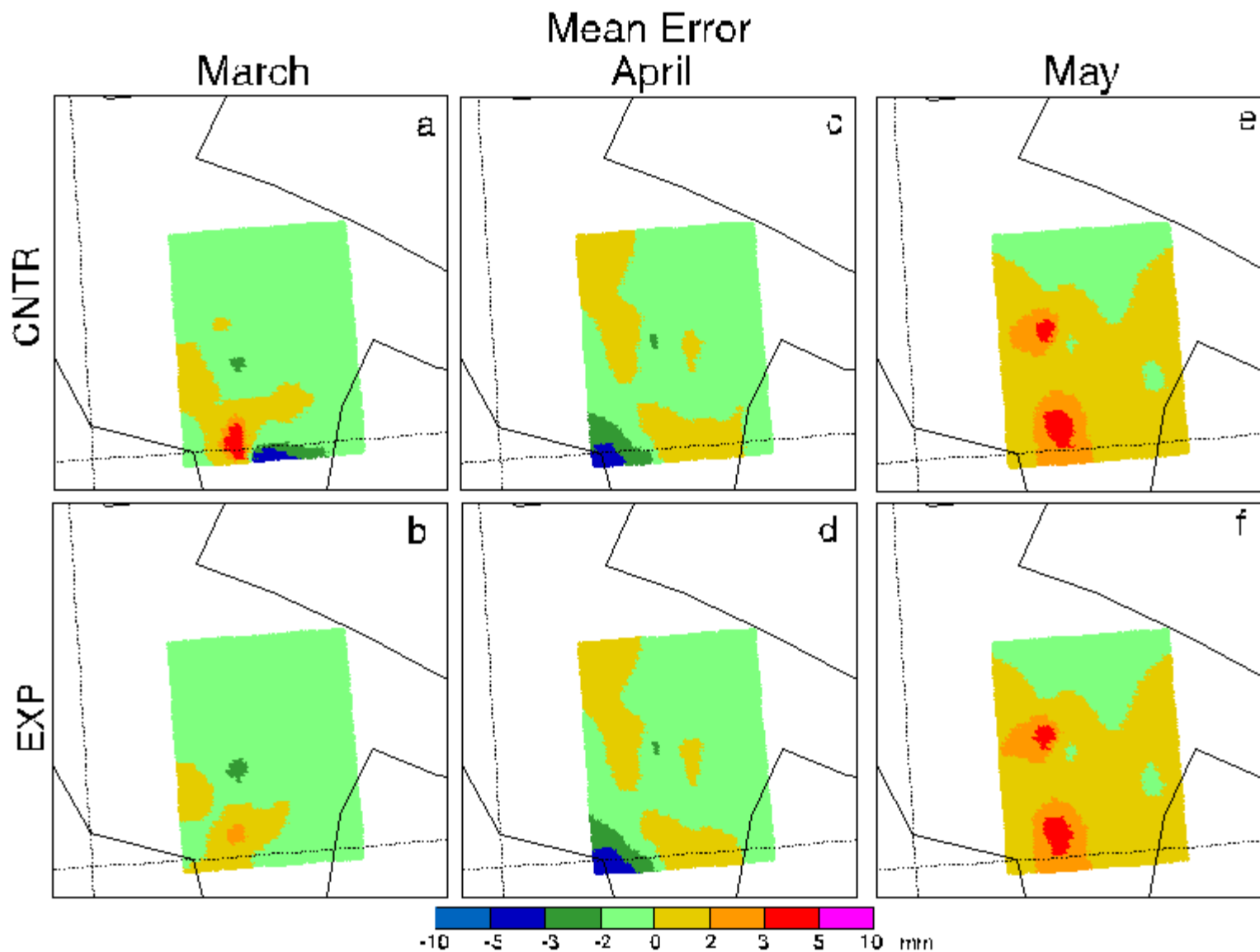


● GPS

40 N

\* Pluviometri





# Deployment in Pine Forest

Species  
Loblolly Pine  
Honeylocust



Overhead view of canopy

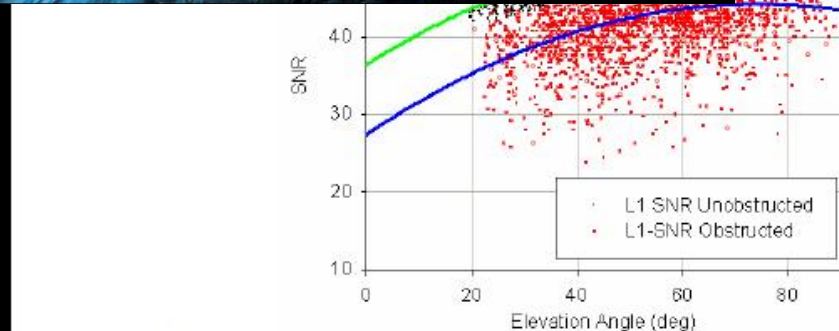
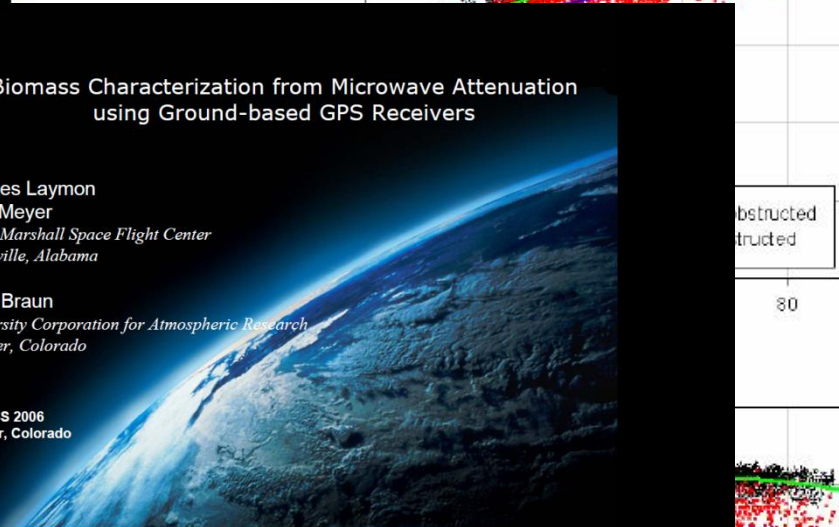
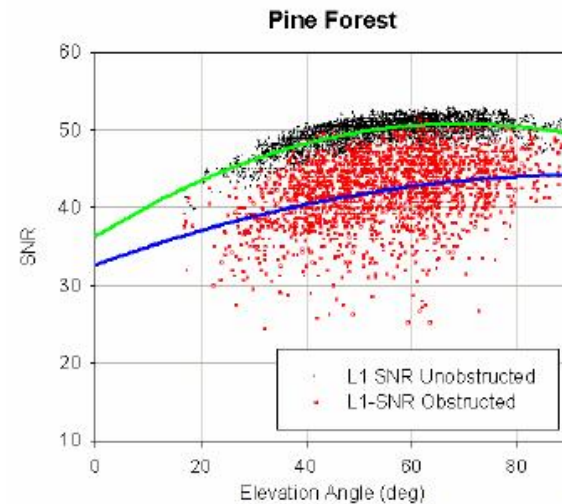
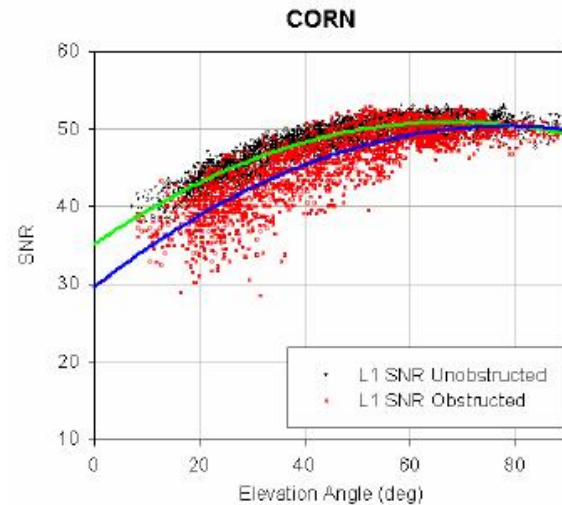
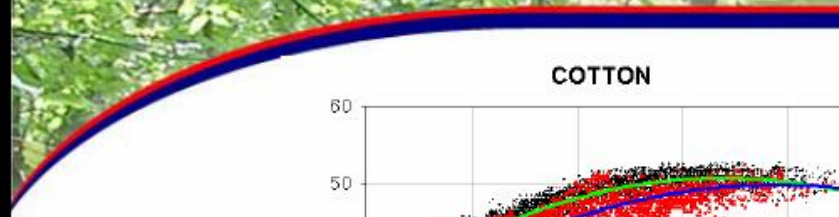


IGARSS 2006, Denver, CO



NASA Marshall Space Flight Center, Earth Science Office

# L1 SNR for Different Vegetation Types



Biomass Characterization from Microwave Attenuation using Ground-based GPS Receivers

Charles Laymon  
Paul Meyer  
NASA Marshall Space Flight Center  
Huntsville, Alabama

John Braun  
University Corporation for Atmospheric Research  
Boulder, Colorado

IGARSS 2006  
Denver, Colorado

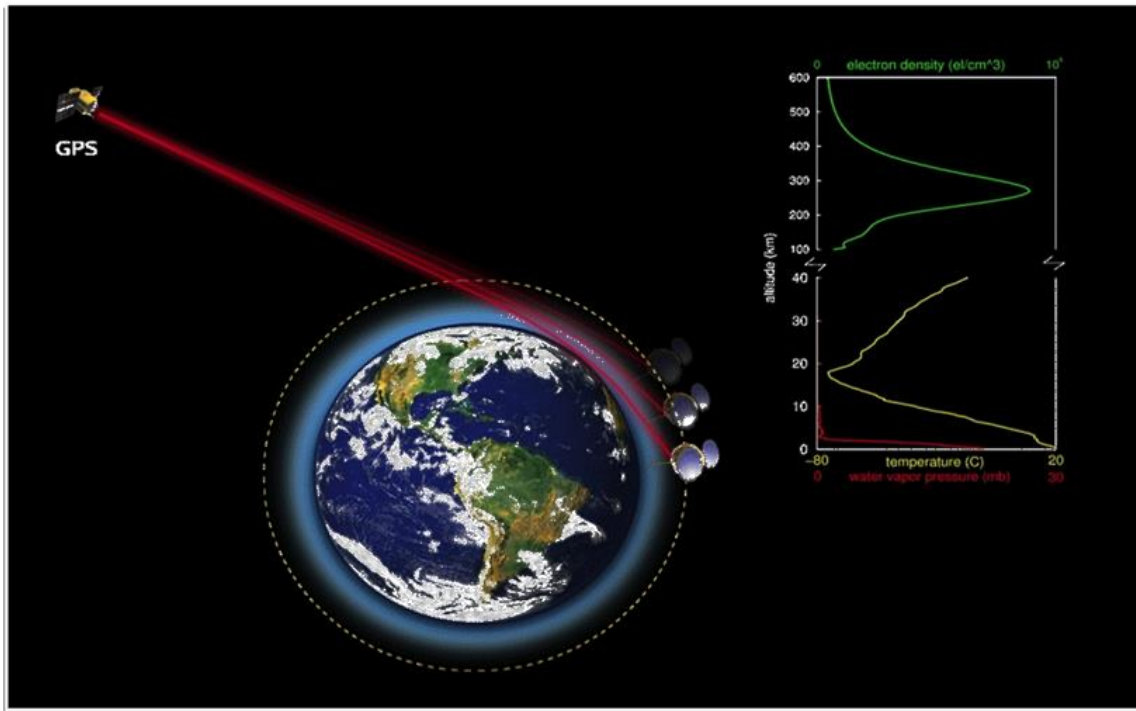
IGARSS 2006, Denver, CO

NASA Marshall Space Flight Center, Earth Science Office

# Potentials App. of GNSS with Limb Pointing Antennas



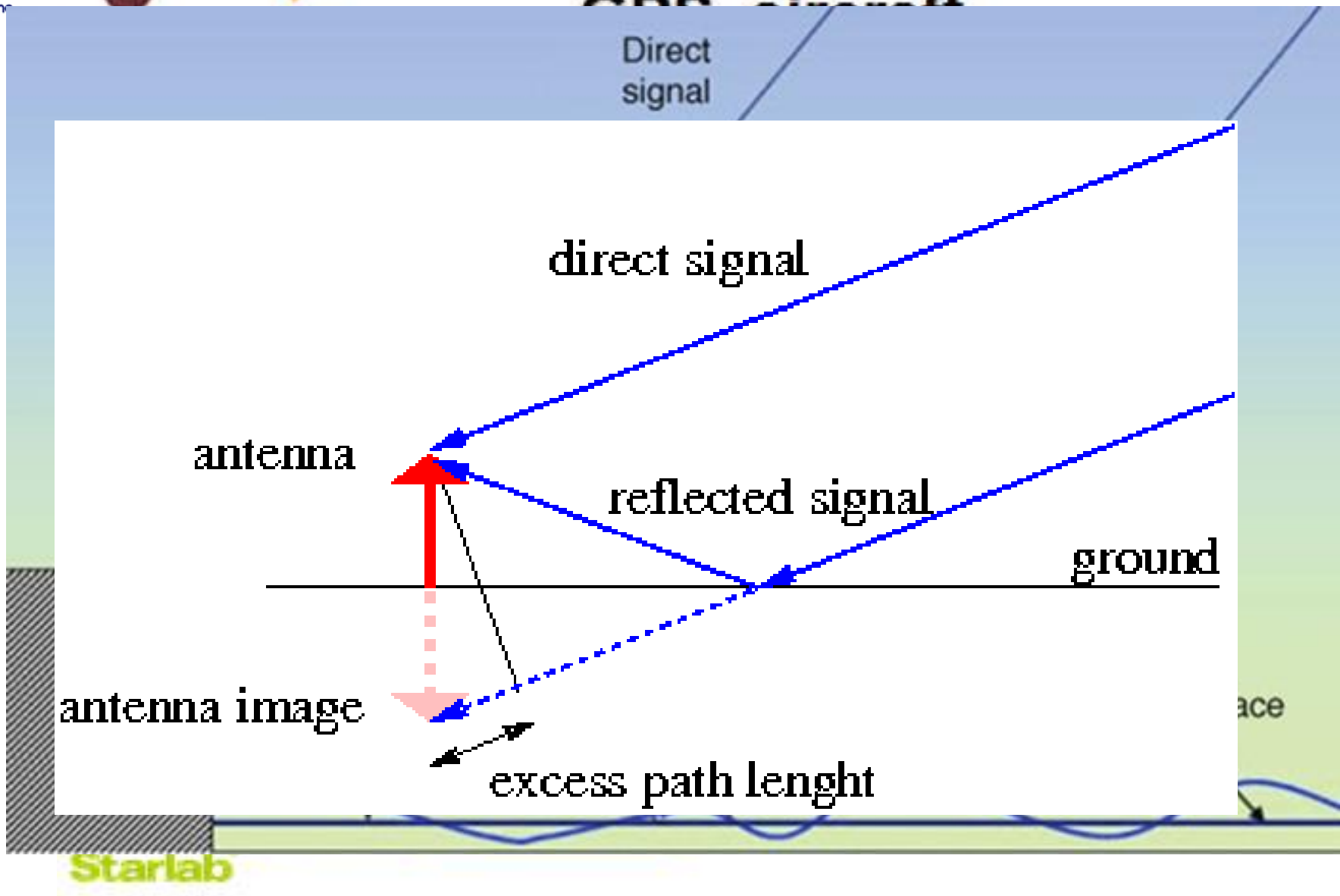
# Radio Occultation



- Limb Directed antenna
  - Climate
  - Meteorology
  - Space Weather

# Potentials App. of GNSS with Upside down Pointing Antennas (Ground and Spaceborne)





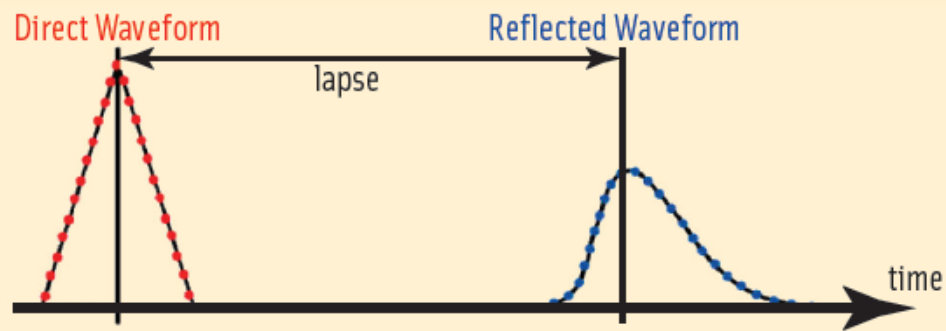


FIGURE 1 Direct and reflected correlation peak (From the article by F. Soulat *et alia* cited in Additional Resources)

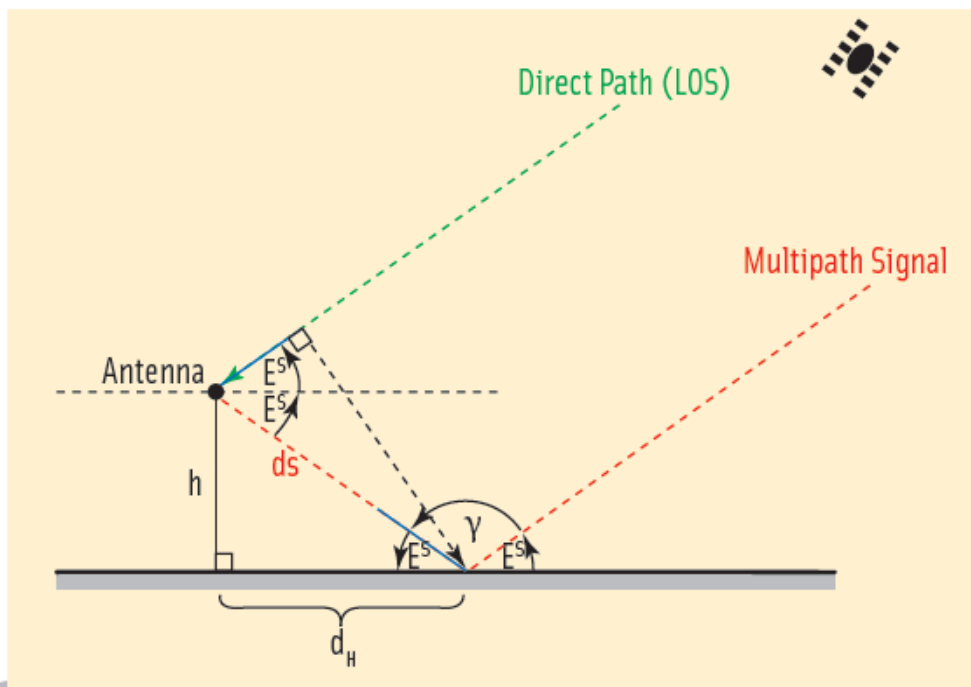
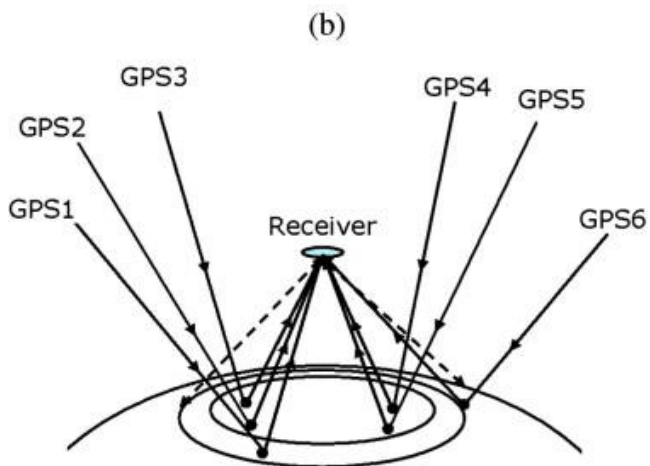
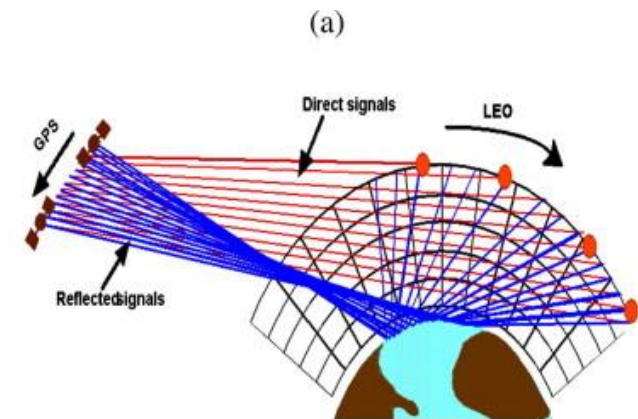


FIGURE 2 Use of ground multipath for altimetry (after M. Irsigler, Additional Resources)



## GNSS Reflectometry:

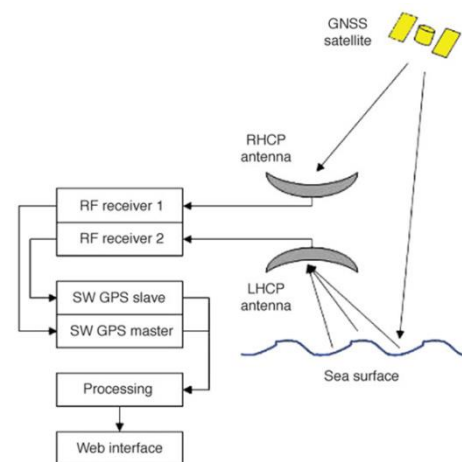


### =====Land=====

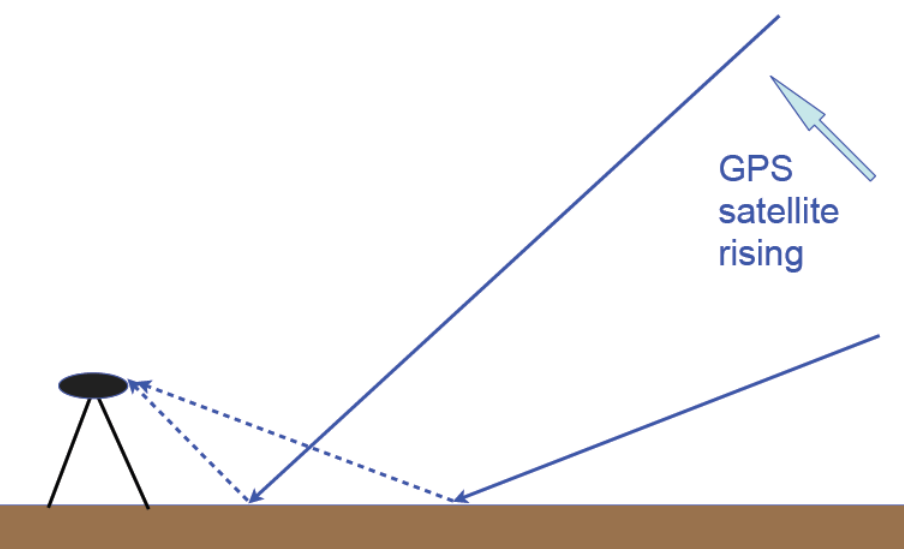
- Ocean height
- Wind speed
- Wind direction

### =====Land=====

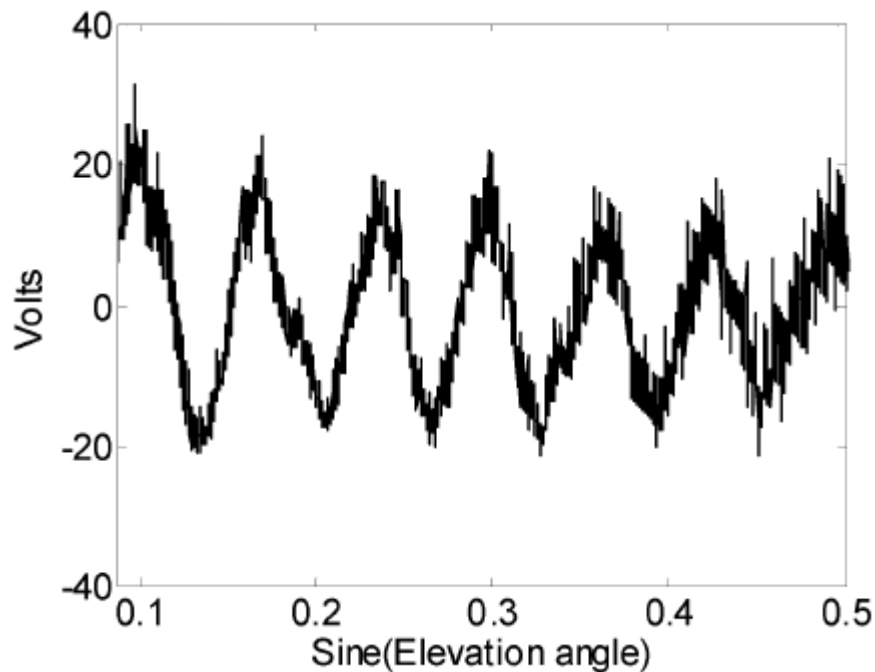
- *Soil moisture*
- Ice and snow thickness
- ***Biomass thickness***



# Use interference pattern to estimate hydrologic variables



Detrended multipath signal



Soil moisture → phase shift

Snow depth → frequency

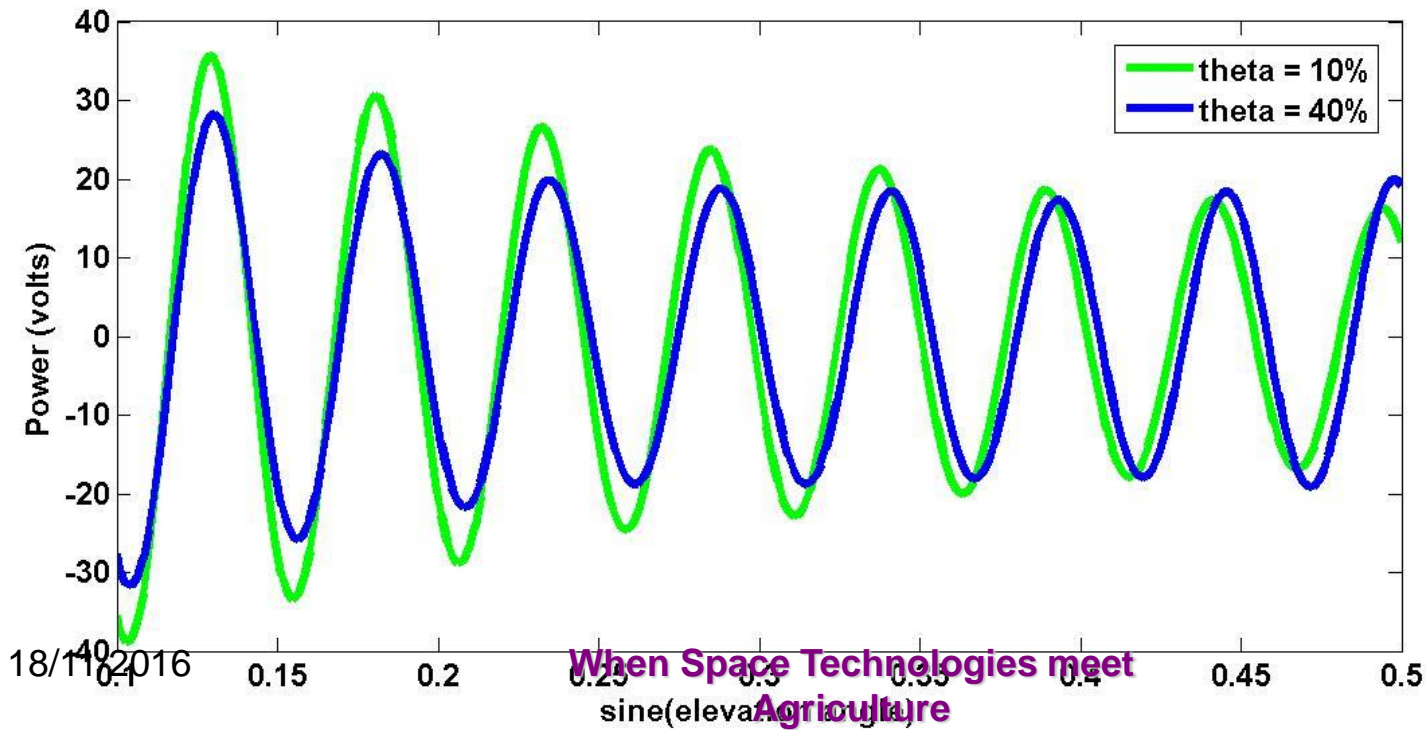
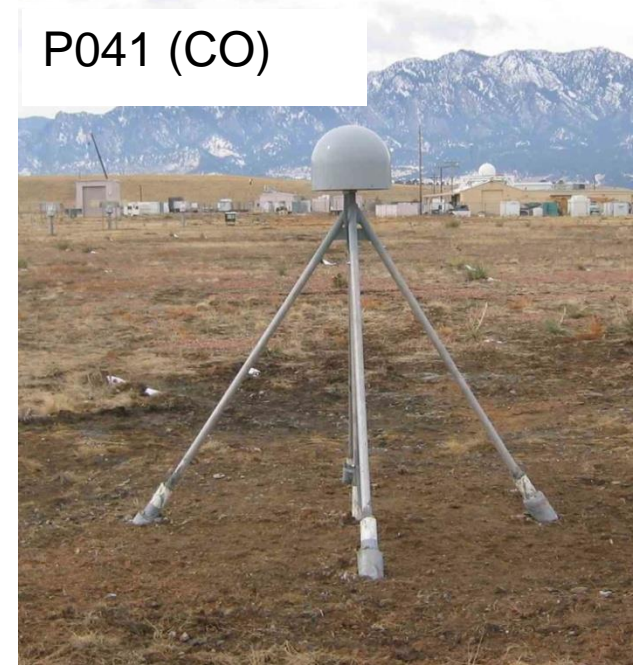
Vegetation → amplitude & MP1

# Soil Moisture

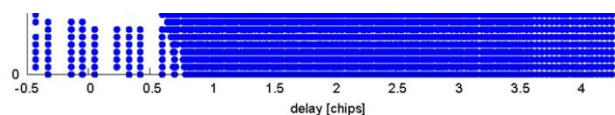
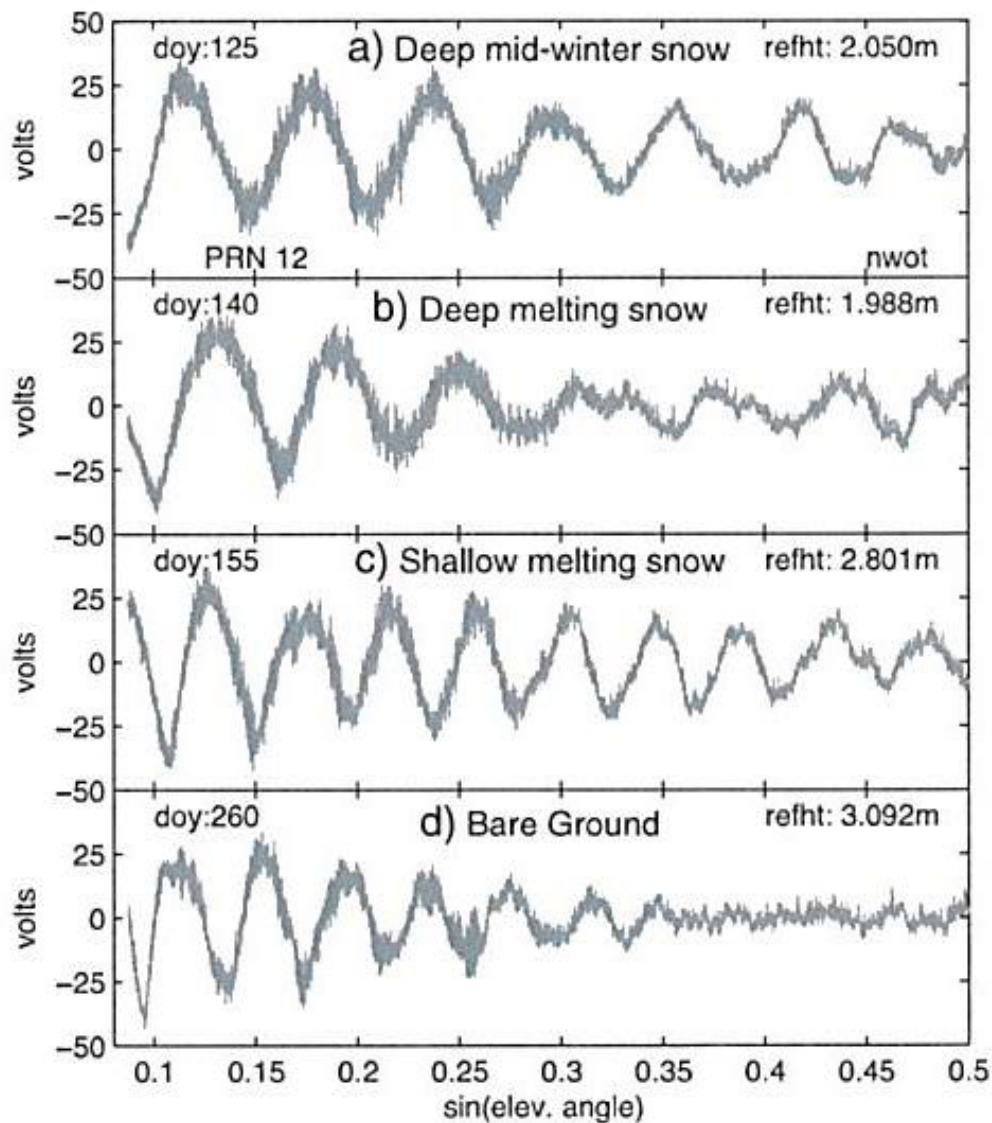
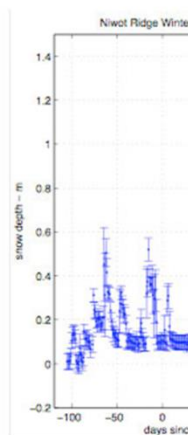
volumetric water content is linearly related to phase of interference pattern

$$SNR = A \cos(f \sin E + \phi)$$

P041 (CO)



# Snow ai



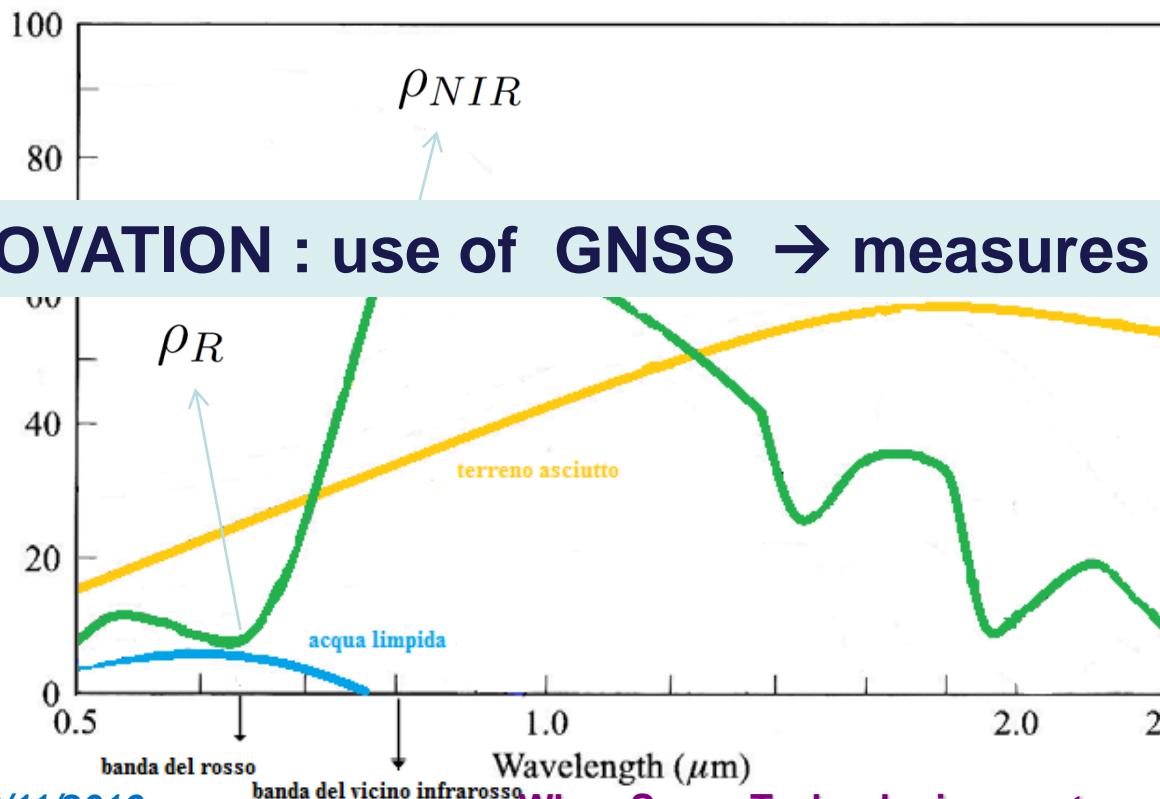
### Vegetation Robustness →

capacity for growth and survival of the plant

Relevant for :

- ↪ Vegetation Robustness maps
- ↪ Precise Farming **and forestry**

STATE of ART for the estimate of the Vegetation Robustness → **NDVI**



$$NDVI = \frac{\rho_{NIR} - \rho_R}{\rho_{NIR} + \rho_R}$$

### INNOVATION : use of GNSS → measures of MP1

Optical Sensors:

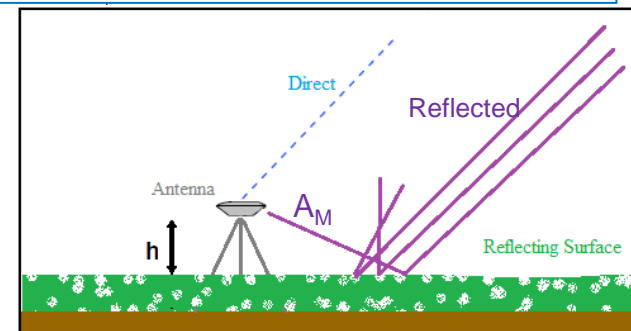
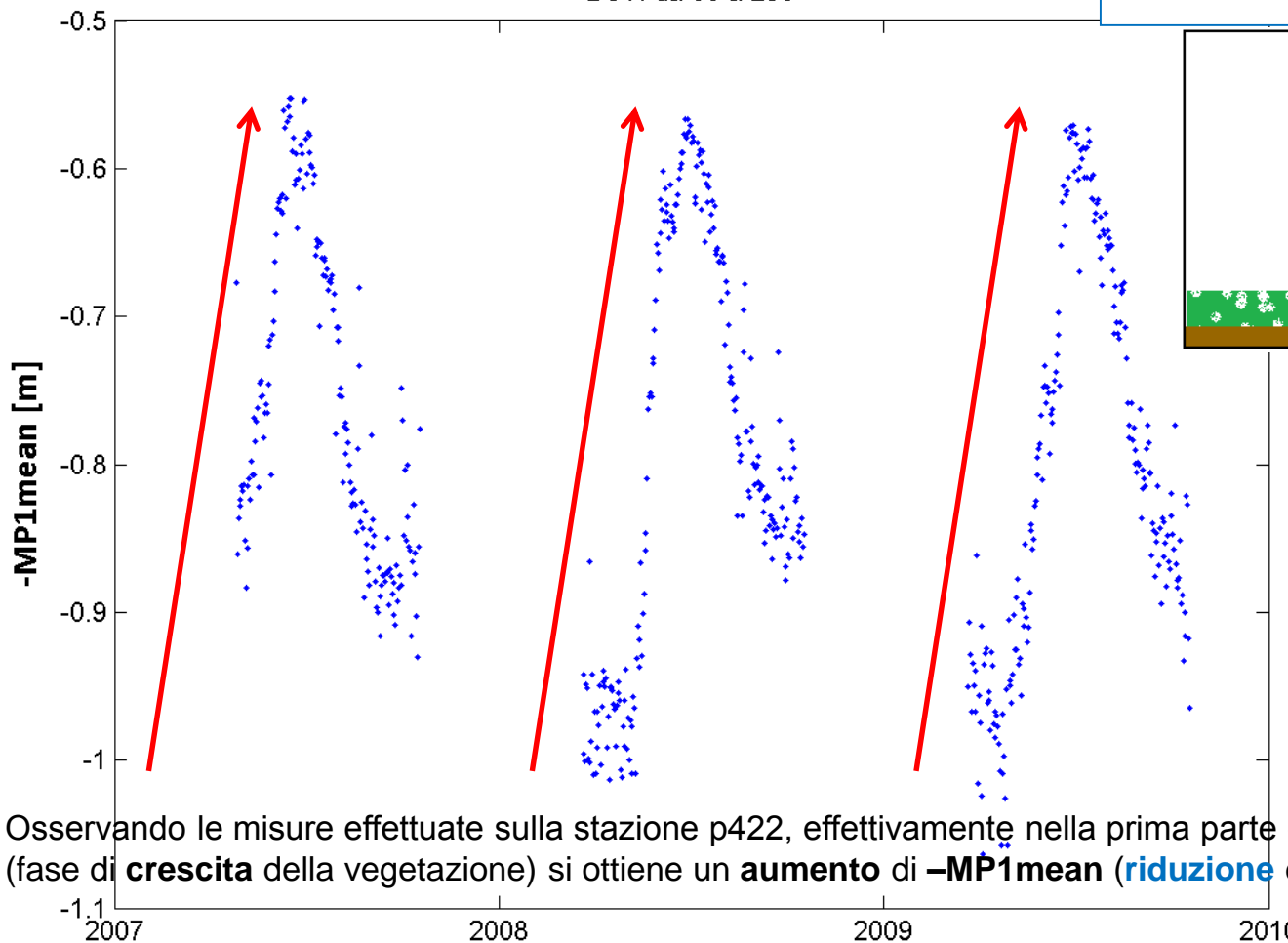
- ↪ **Rover** (GreenSeeker)
- ↪ **airplanes-Drones**
- ↪ **Satellites**  
(LANDSAT, MODIS, etc...)

## COSA DICE IL MODELLO MATEMATICO di MP1mean(g)

### Fase di crescita della vegetazione

Stazione: p422  
 Elevazione tra 5° e 20° - Azimuth tra 0° e 360°  
 DoY: da 80 a 290

$$|MP1_{mean}(g)| \propto A_M(g) \times h(g)$$



#### Fase di crescita

- si riduce  $h$
- si riduce  $A_M$
- si riduce MP1mean

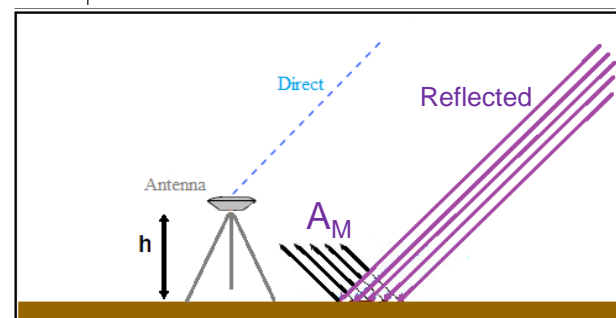
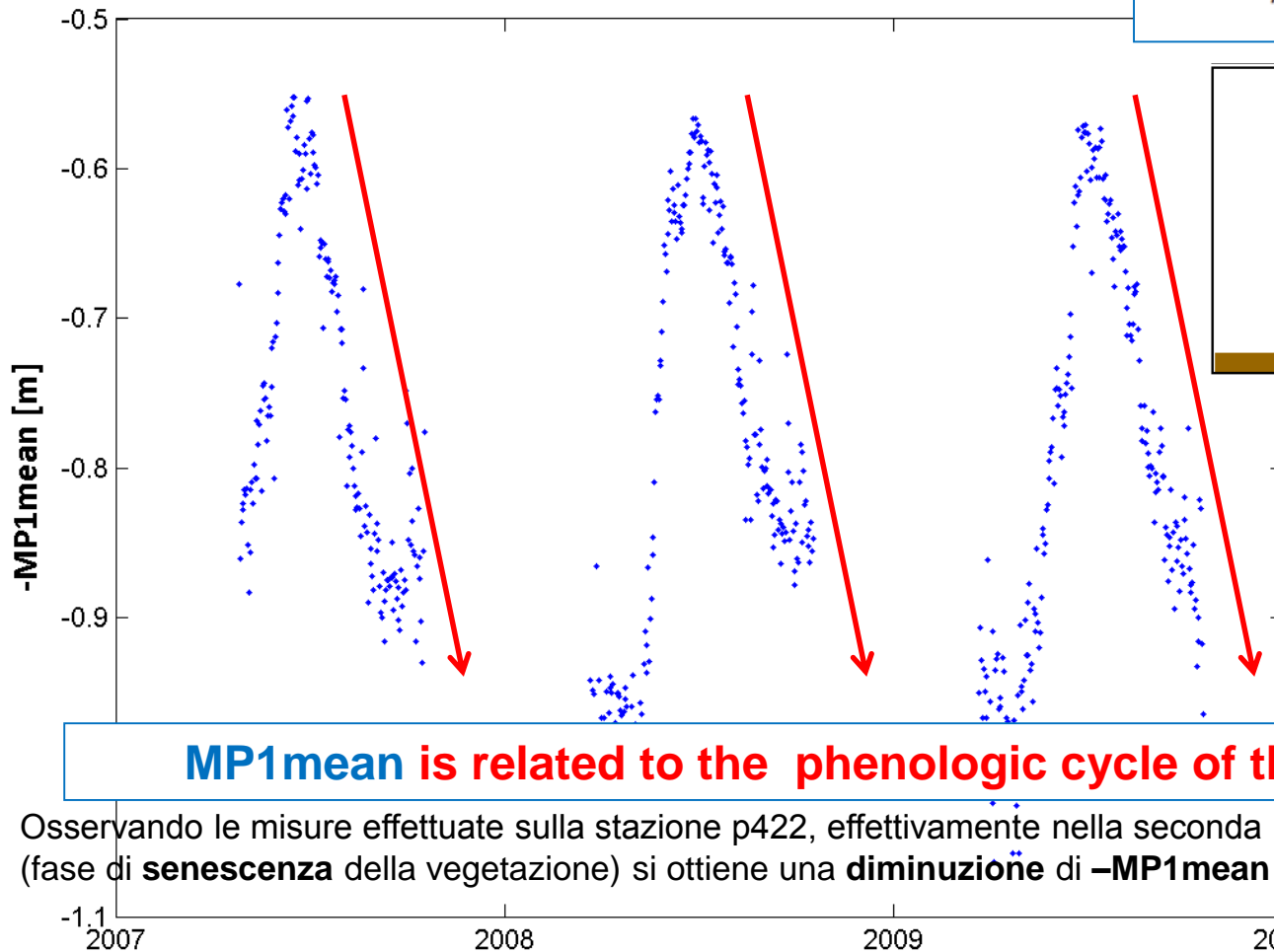
Osservando le misure effettuate sulla stazione p422, effettivamente nella prima parte dell'anno (fase di **crescita** della vegetazione) si ottiene un **aumento** di **-MP1mean** (**riduzione** di **MP1mean**)

## COSA DICE IL MODELLO MATEMATICO di MP1mean(g)

### Fase di senescenza della vegetazione

Stazione: p422  
 Elevazione tra 5° e 20° - Azimuth tra 0° e 360°  
 DoY: da 80 a 290

$$MP1_{mean}(g) \propto A_M(g) \times h(g)$$



#### Fase di senescenza

- aumenta h
- aumenta  $A_M$
- aumenta MP1mean

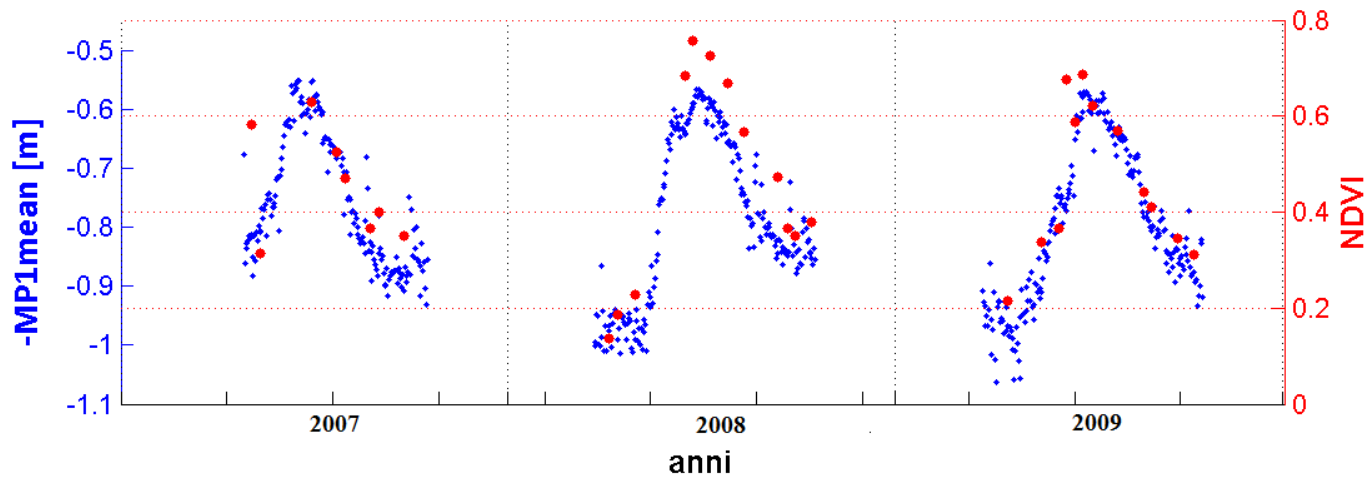
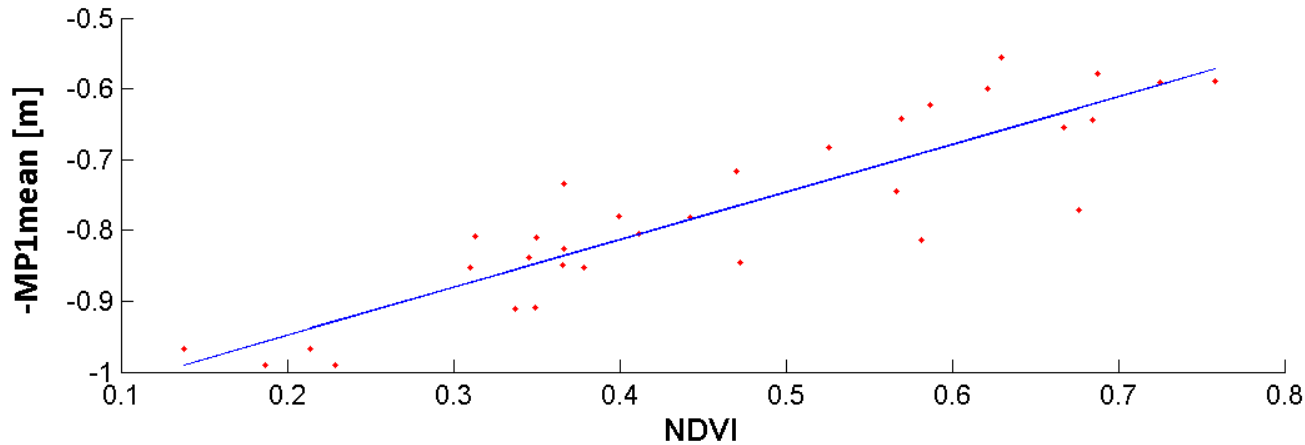
**MP1mean is related to the phenologic cycle of the vegetation**

Osservando le misure effettuate sulla stazione p422, effettivamente nella seconda parte dell'anno (fase di **senescenza** della vegetazione) si ottiene una **diminuzione** di **-MP1mean** (**aumento** di **MP1mean**)

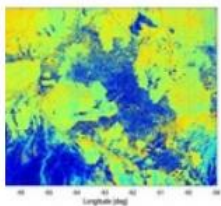
## Comparison between **MP1mean** e **NDVI (LANDSAT)**

Anni concatenati - Stazione p422

$$R^2 = 0.792161$$





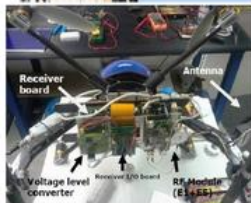


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# COREGAL: Combined Positioning-Reflectometry Galileo Code Receiver for Forest Management

By Izabela Prates | 17h14, 13 de March de 2015

Coregal aims at developing a low cost unmanned aerial platform and service for biomass mapping will allow wide scale mapping in the Brazilian context of forest management. A first of a kind combined Position-Reflectometry Galileo receiver is developed as main sensor for platform positioning and biomass estimation, the latter using reflected Global Navigation Satellite Systems (GNSS) signals (also called GNSS-R) that propagate through tree canopies,



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# Conclusions

- The cheap cost of GNSS receivers and their very high performances (few mm in positioning and few hundredth of mm in phase measurements) allows a wide field of applications of GNSS in Remote Sensing (Geophysics, Meteorology, Climate, Space Weather, etc)
- Some applications can be helpful and sound very promising for Precision Farming...
- ASI/CGS has developed till now only geodetic/meteo applications but the plan is to cover also special applications like PF
- **The broader band of GALILEO will enhance the performances of RS GNSS !!**