
SAFEPORT: Project presentation



SAFEPORT is partially funded by the European Commission and the project is carried out in the context of the Galileo FP7 R&D programme supervised by European GNSS Supervisory Authority



Title

Safeport

Date:

17.04.2012

Location:

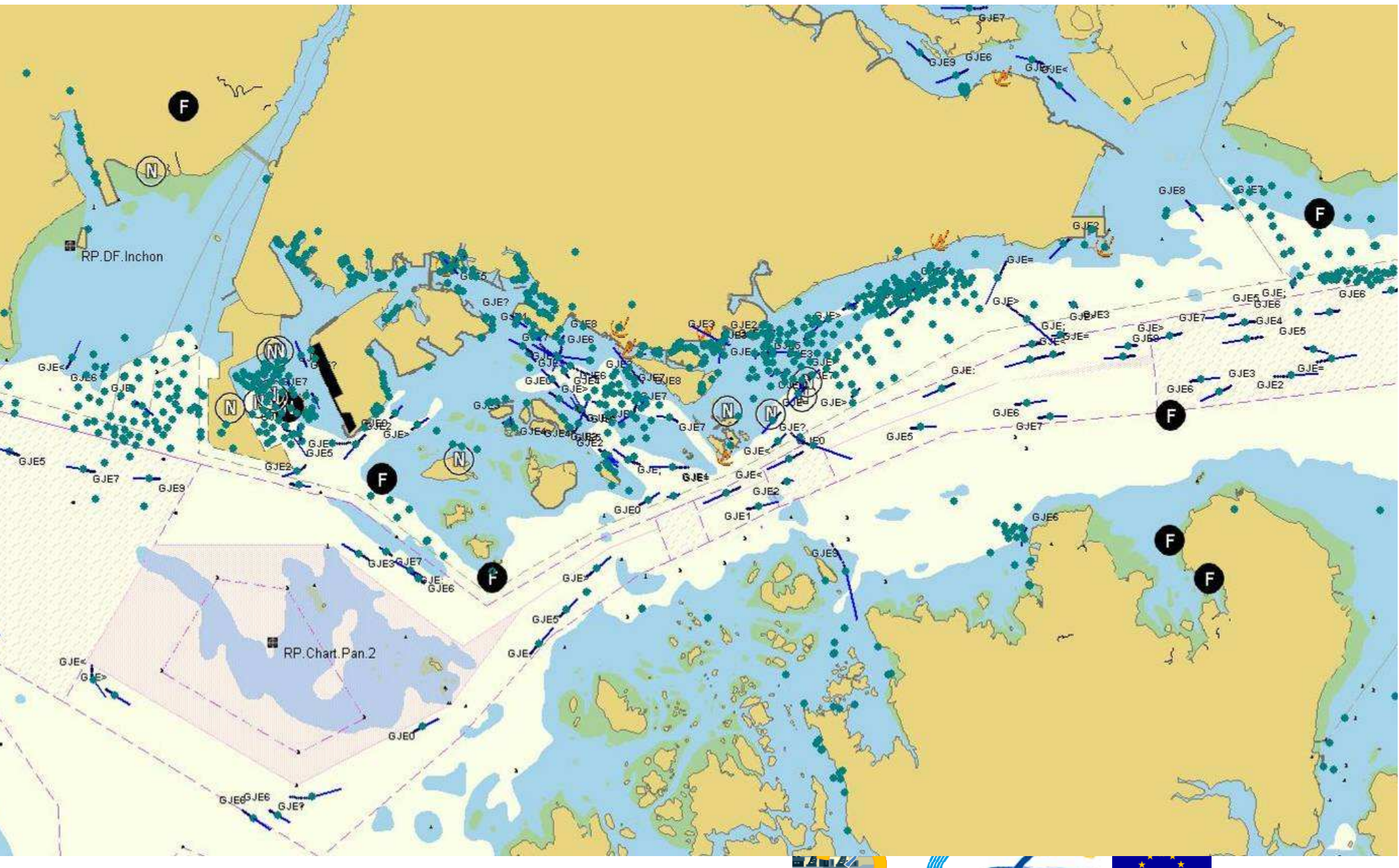
Venice Nereus conference

Presenter:

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(bhodgson@bmtmail.com)



Current situation: Traffic management challenge



Current situation: AIS/GPS

Vulnerable to: Jamming, Spoofing, Lying



Radar picture



ECDIS based on
GPS



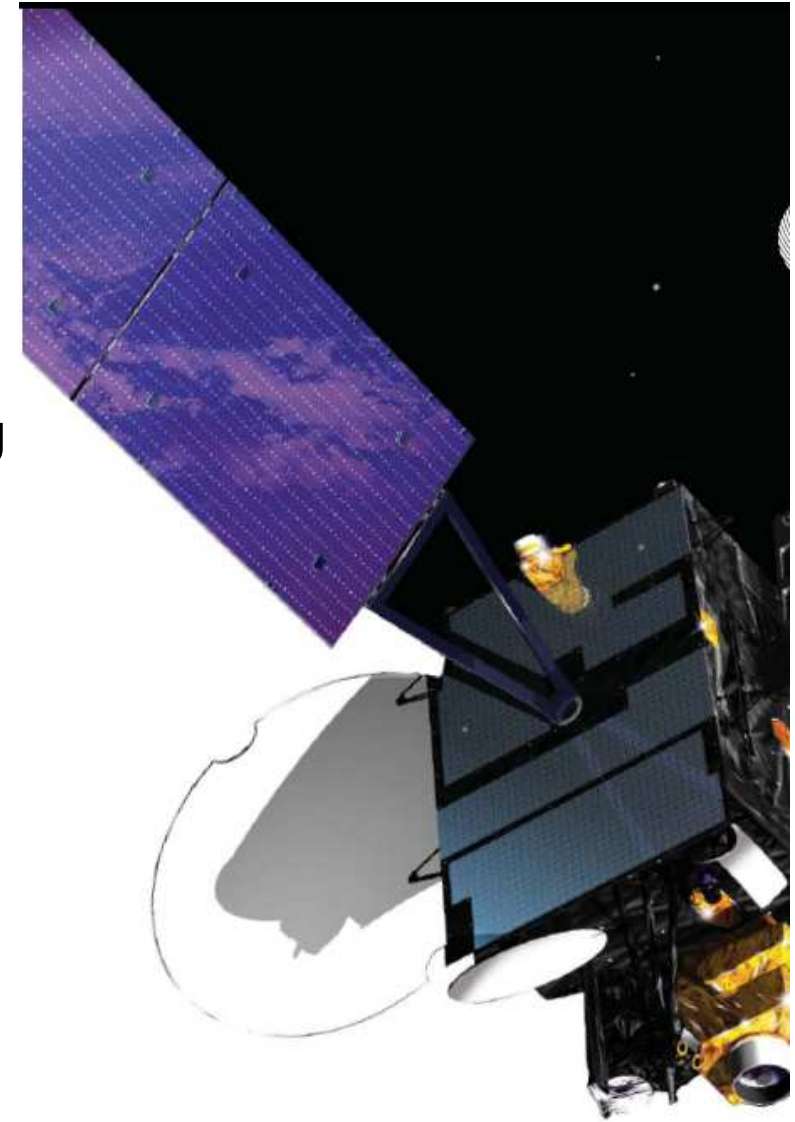
Safe Port Operations using EGNOS safety of life Services

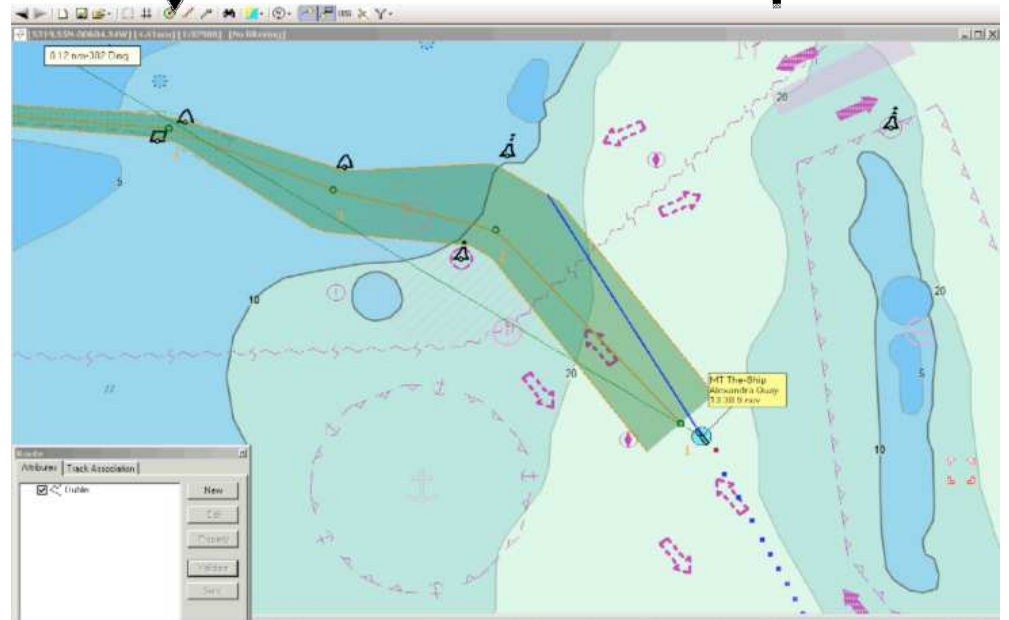
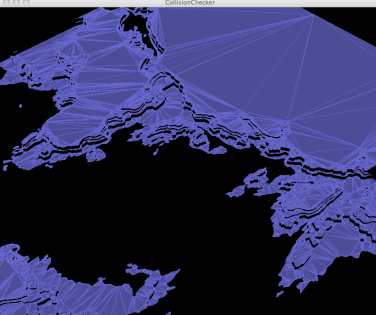
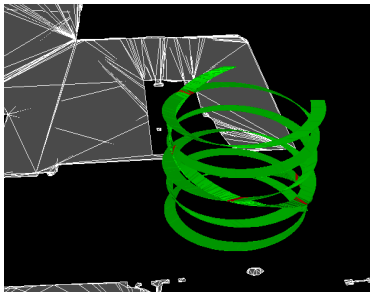
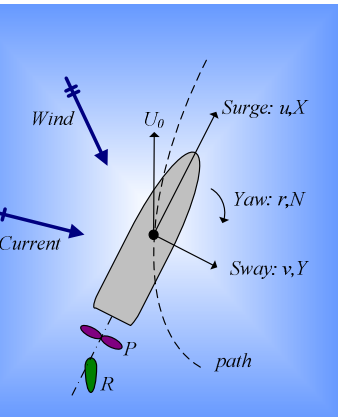
Enhancing security

- Encrypt and authenticate position reports (Anyone can broadcast AIS reports claiming to be any ship)
- Protect against GPS jamming and spoofing
- Guarantee on accuracy of position information using EGNOS protection level (Galileo).

Enhancing cooperation

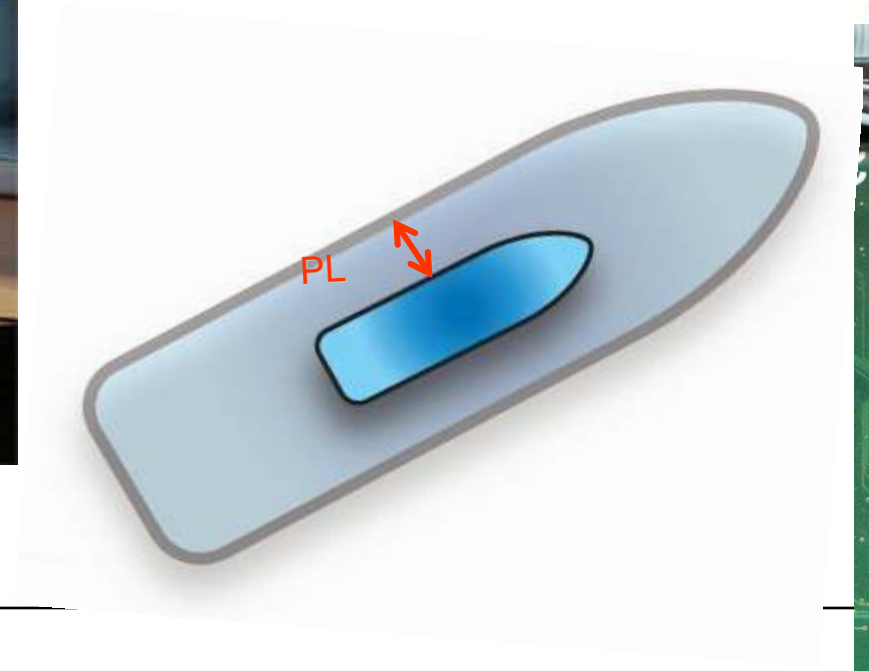
- Electronic communication between pilot and VTS
- Ships agree to follow channel in space & time
- Channels are validated to ensure they are safe and do not conflict





Safepilot

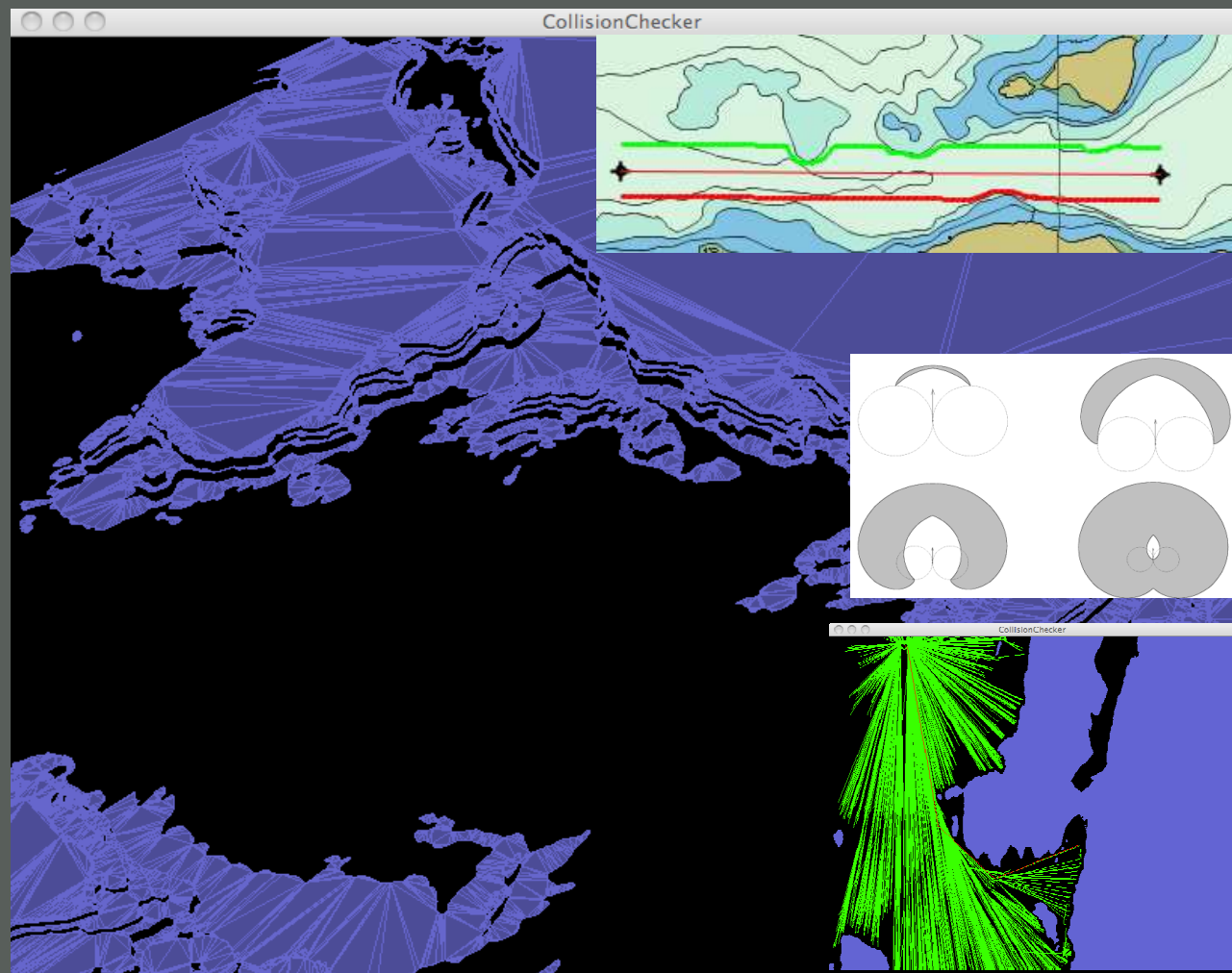
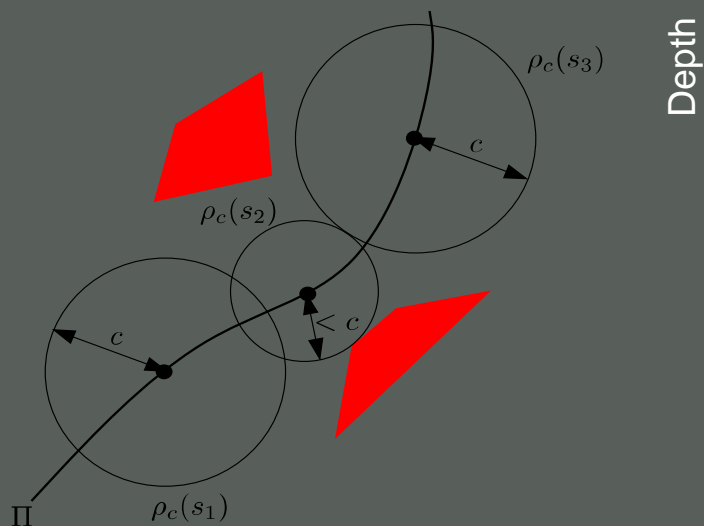
The algorithm for PL computation has been embedded in the hardware of the Pilot Portable Unit (SafePilot) which include two professional GPS devices, a processing unit and a tablet for the HMI.





Validation: **Static Path**

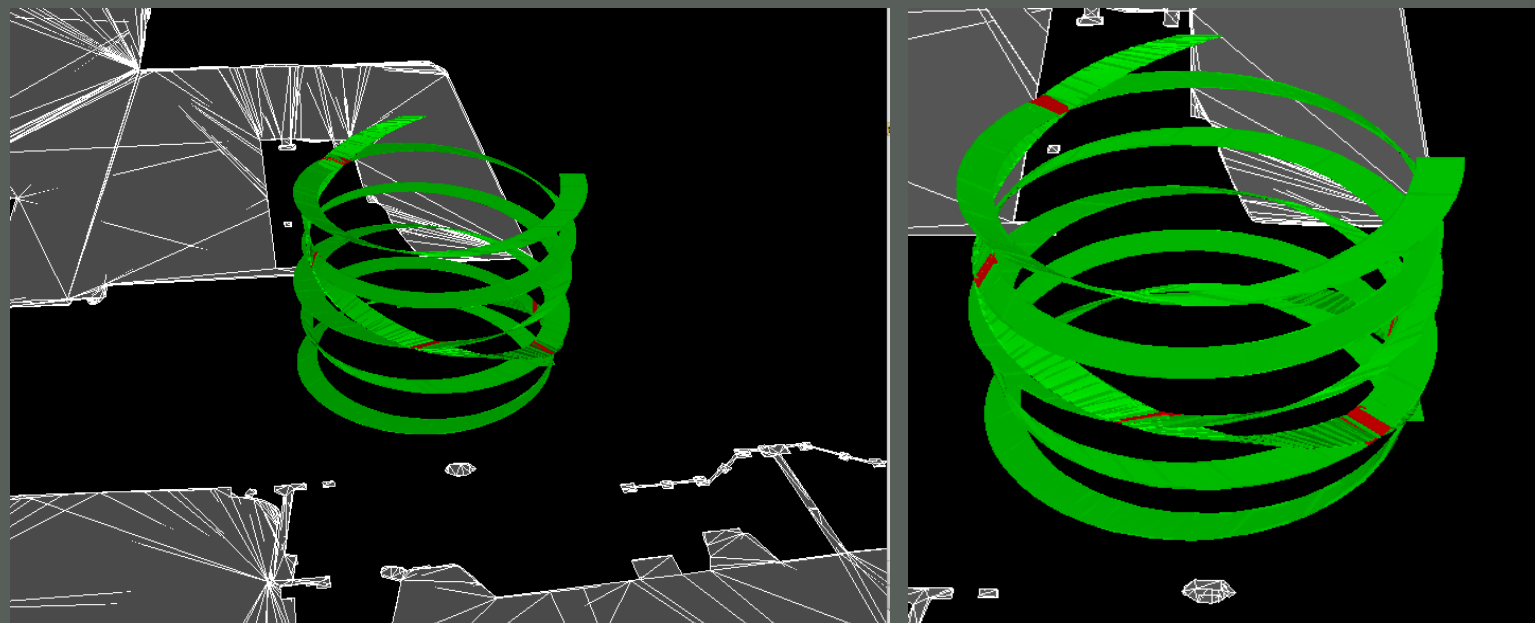
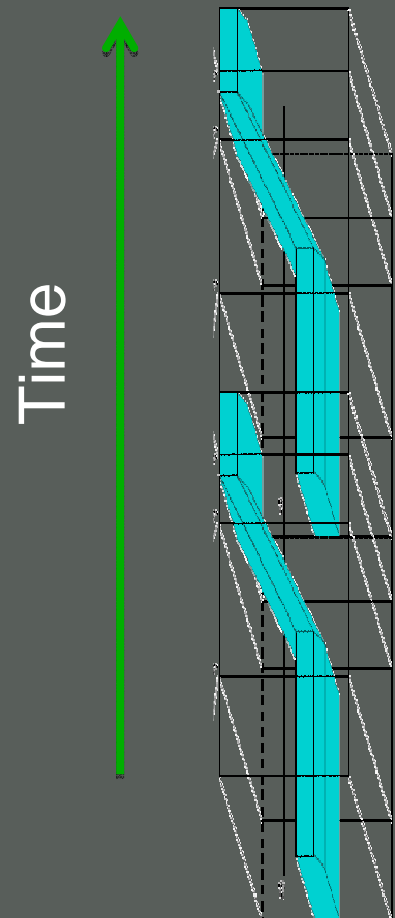
- Land
- Restricted areas
- Regulations
- Dynamic Under Keel clearance
- Feasible manoeuvres



Tested with S57
Needs Detailed Bathymetric information

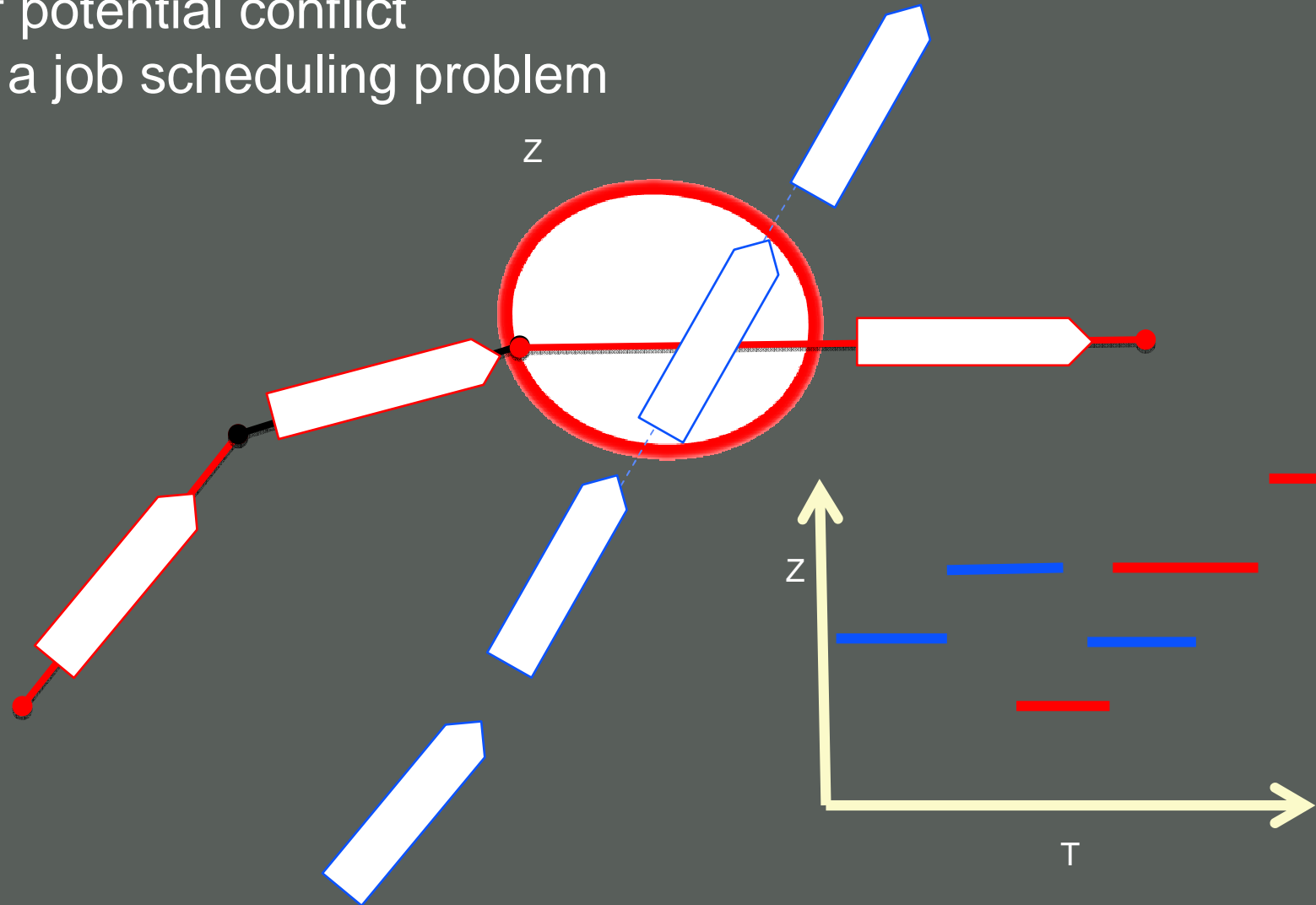


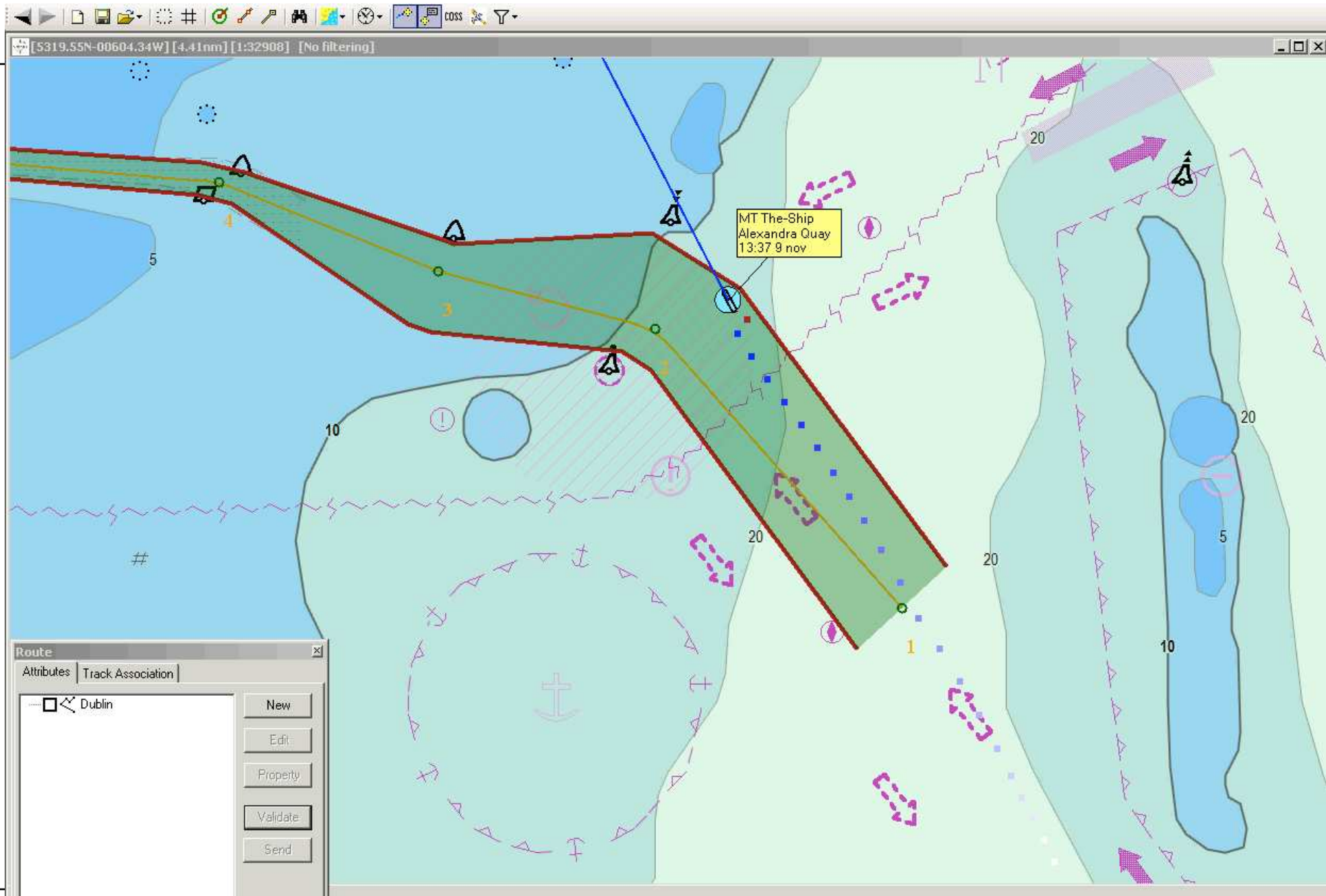
Validation: Dynamic Path



Planning: **Dynamic slot allocation**

- Geographic paths are fixed
- Identify areas of potential conflict
- Reduces this to a job scheduling problem





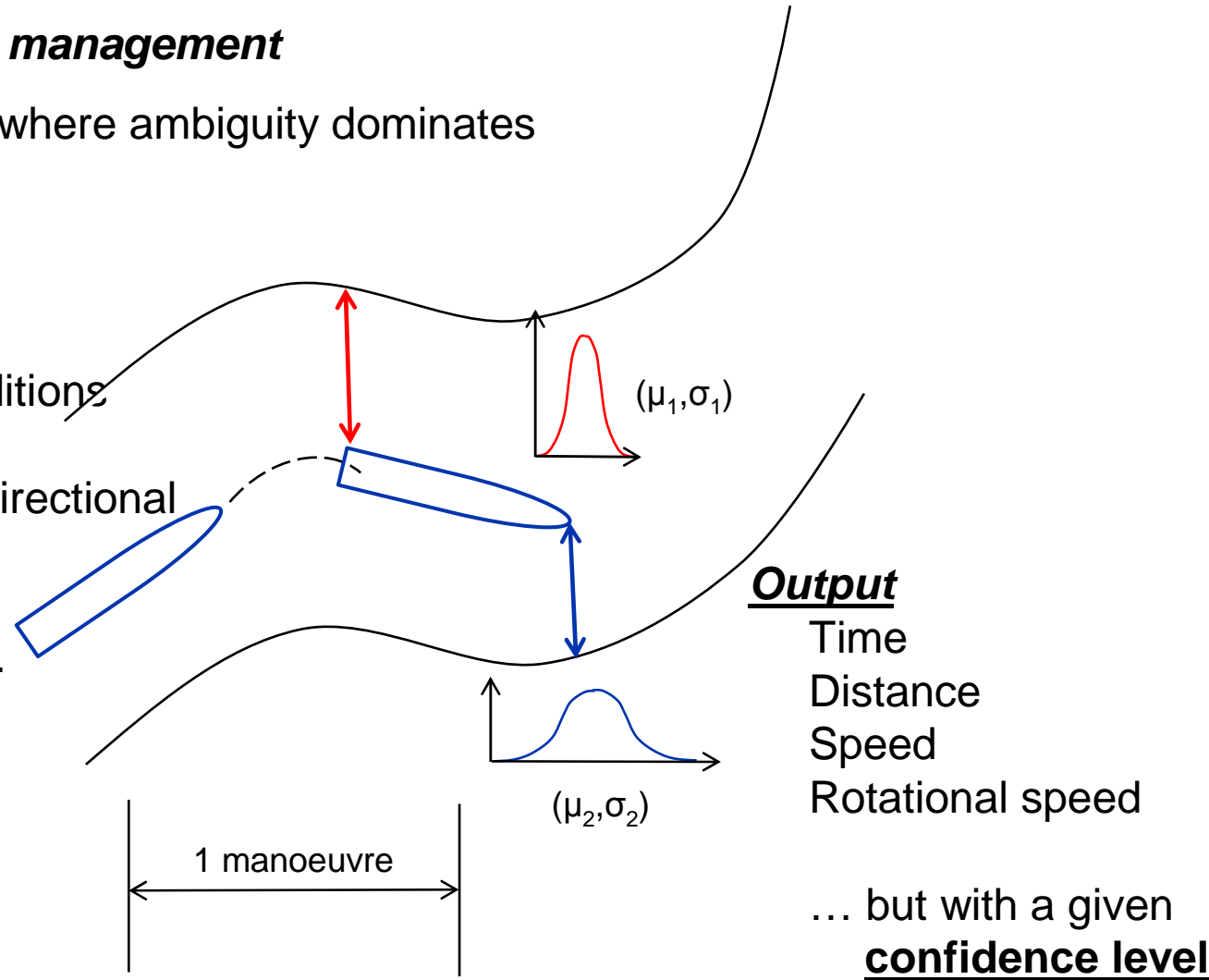
Additional functionality

Probabilistic mode – *Uncertainty management*

Assessment of a situation in cases where ambiguity dominates

- **Input / scenario**

- Approaching speed
 - Displacement and draught
 - Rapidly changing wind conditions
 - “Non-responsive” crew
 - Large ships have inherent directional instability
 - Etc.
- ... and combinations of the above.



E-Navigation benefits of SafePort....

- Digital information exchange
- Traffic Organization (TOS)
- Navigational Assistance (NAS)
- Maneuvering Support
- Vessel monitoring

Galeleo/EGNOS including it's SOL service is a vital component Making GNSS based systems more reliable, (WAAS-EGNOS) the uptake of the technology can increase.



Future work: **Beyond Safeport**

Large scale E navigation test case to prove and improve

Focus on: latency, security, robustness.

Hybrid communications system to extend concept into open sea.

Satellite communications

Shore based communications

Ship 2 Ship communications

Incorporate live global met ocean data.

Integrate with ship systems



Long term vision

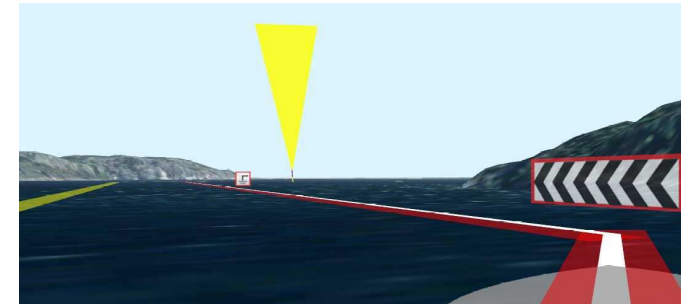
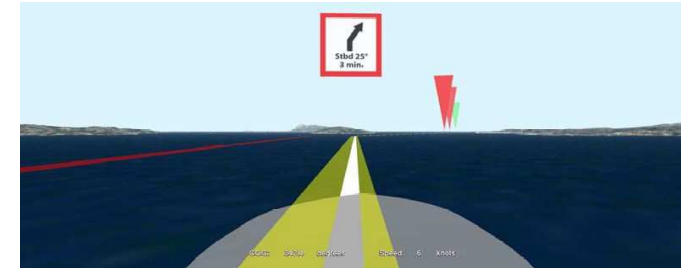
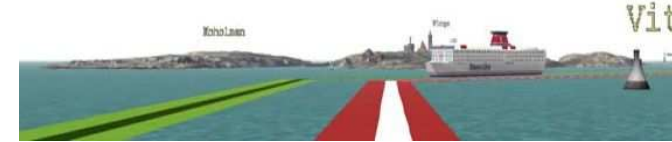
All global maritime traffic is actively managed

Safe management of traffic

Real time coordinated optimization.

Port slot times

Integration with rest of logistics network



Future: vision



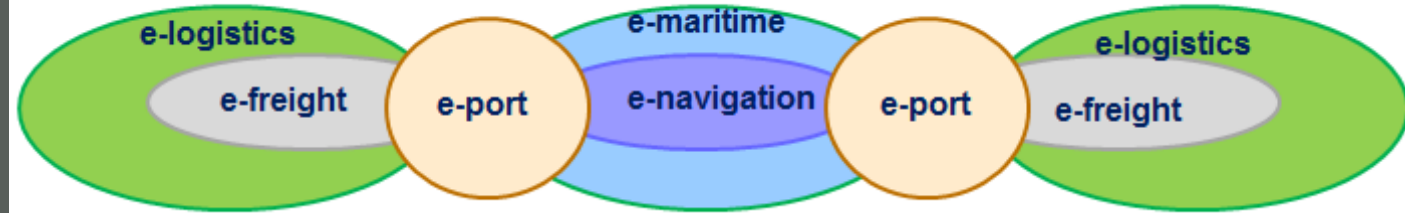
Hinterland

Port

Maritime
Transport

Port

Hinterland



Future: **vision**



Given:

Status of vessels

Status of cargo

Weather

& Some
models

Transport requirements

Optimise:

On time delivery

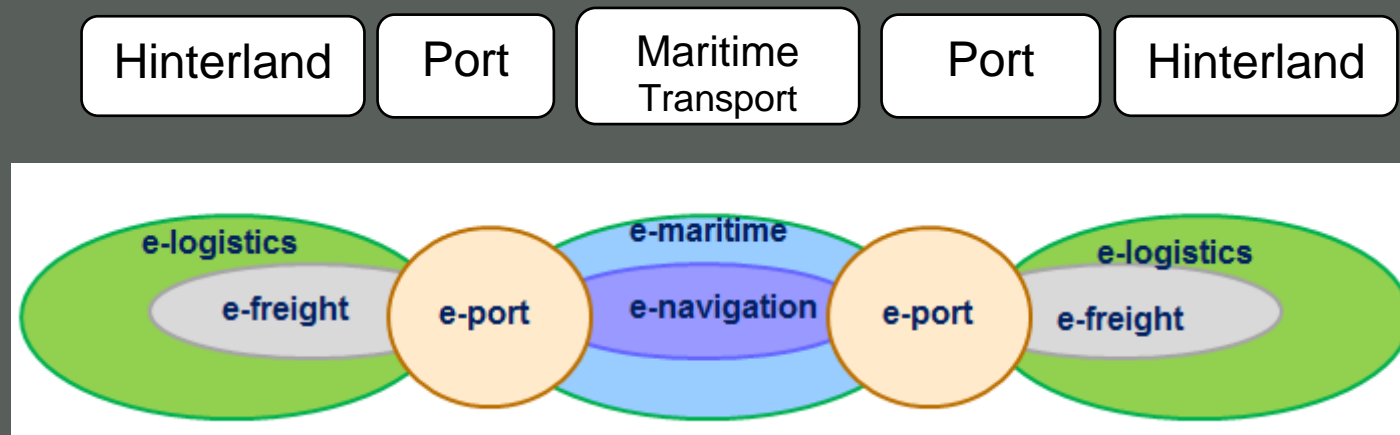
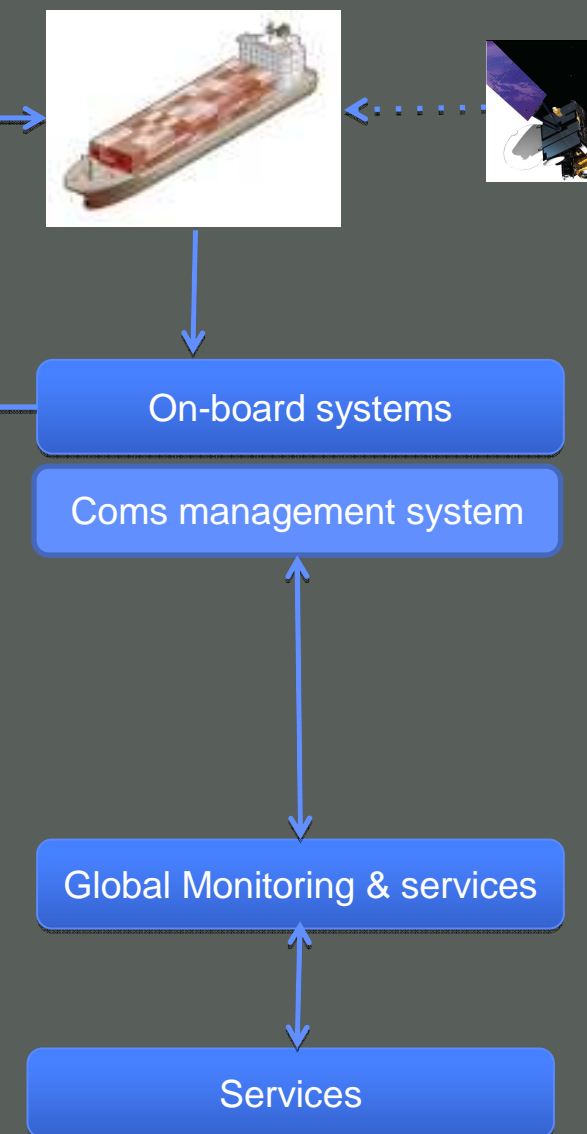
Fuel consumption

Safety

For multiple (possibly competing) agents



Future: vision



Global : Monitoring
Global : Information sharing
Global : Optimisation



Thank you



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